Subject: Mechanics of Materials (MEC301)

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chapter-01 : FORCE

Defination of force :-

Force is defined as an external agency either push or pull which changes or tends to change the state of rest or uniform motion of a body upon which it act.

unit of Force :-

→ S.I. unit of Force = Newton(N) $1N = 1 \text{ Kgm} \overline{s}^2$

→ CGS unit of Force = Dyne → FPS unit of Force = poundal

Types of forces

1. Tensile force: - The force which acts away from the point of application is called tensile force.

2. Compressive Force: - The force which acts towards the point of application is called compressive force.



3. Shear Force: - A force which acts parallel or tangential to the plane under consideration is called shear force. PA TITARA



Resolution of a Force: -

The way of sepresenting a single force into number of forces without changing the effect of the force on the body is called as resolution of a force.

Methods of Resolution :-

There are two methods of resolution.

- 1. Resolution of a force into two mutually peopendicular components.
- 2. Resolution of a force into two nonperpendicular components.
- 1. Resolution of a force into two mutually perpendicular components

Wet a force 'F' be inclined at an angle 0 to x-axis as shown in tigure. Length OA represent the magnitude of F. W& have to resolve it into two components Fx along x-axis and Fy along y-axis



Draw perpendicular from A to point B on X-axis. Length OB represent the magnitude of x-component and AB represent the







: $F_n = F \cos 0 = 100 \cos 0^\circ = 100 \times 1 = 100 \text{ N}$: $F_y = F \sin 0 = 100 \sin 0^\circ = 100 \times 0 = 0$

Case (ii): If the force acts from
$$(0,2)$$
 towards
 $(-1,2)$ i.e. for izontally towards left, $0=180^{\circ}$
from the X-aris.
 $\therefore F_{X} = F\cos\theta = 100\cos 180^{\circ} = 100\times(-1) = -100 \text{ N}$
 $\therefore F_{X} = F\sin\theta = 100 \sin 180^{\circ} = 100\times0 = 0$
 $\boxed{\text{case (i)}}$ $F_{X} = 100 \text{ N}$, $F_{Y} = 0$
 $\boxed{\text{case (i)}}$ $F_{X} = -100 \text{ N}$, $F_{Y} = 0$
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 $\boxed{\text{case (i)}}$ $F_{X} = -100$



Find: Refangular Components
$$F_x$$
 and F_y
Let us assume that both the forces (10 N
and 20 N) are puch.i.e. They act away
from the origin.
(i) Components of 10 N passing through (0,0) and (0,2)
Here, $F = 10 N$, $D = 90^{\circ}$ from the X-axis
Negnow that,
 $F_x = F \cos \theta = 10 \cos 90^{\circ} = 10 \times 0 = 0$
 $F_y = F \sin \theta = 10 \sin 90^{\circ} = 10 \times 1 = 10 N$
(ii) Components of 20 N passing through (0,0) f(-2,0)
Here, $F = 20N$, $\theta = 180^{\circ}$ from the X-axis
we know that,
 $F_x = F\cos \theta = 20 \cos 180^{\circ} = 20 \times (-\theta) = -20 N$
 $F_y = F \sin \theta = 20 \sin 180^{\circ} = 20 \times 0 = 0$
 $10 N$ force : $F_x = 0$, $F_y = 10 N$
 $20 N$ force : $F_x = -20N$, $F_y = 10 N$



Besolve a force of 20 N acting North-
East away from the point.
Solution:-
North
Solution:-
North

$$Given: F=30N$$

 $0 = Anyle made by West$
 $force with the x-axis$
 $= 45°$
We know that,
 $F_x = Fcoso$
 $= 30 cos 45°$
 $F_x = 21.21 N$
 $\therefore Fy = Fsin0 = 30 sin 45° = 21.21 N$
 $F_x = 21.21 N$
 $\therefore Fy = Fsin0 = 30 sin 45° = 21.21 N$
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 $\therefore F_y = 50 sin 45° = 21.21 N$
 $\therefore F_$

We know that,

$$F_{x} = F\cos\theta = $25\cos 135^{\circ} = $29 - 17.68N$$

$$F_{y} = F\sin\theta = 25\sin 135^{\circ} = 17.68N$$

$$F_{y} = 100N$$

$$F_{y} = 100N$$

$$F_{y} = 100$$

$$F_{y} = 100 \text{ Cos} 110^{\circ} = -34.2N$$

$$F_{y} = 73.97N$$

$$F_{y} = 93.97N$$

Presolve a force of 5KN inclined at 30°
with X-anis acting towards the point.
Sol^h:-
Given:-F=5KN

$$0 = aclute angle mode$$

by torze with
twe x-anis
= 30°
Find:-Fx and Fy:
we know that
 $F_x = -F\cos 0 = -5\cos 30^\circ = -4.32 \text{ kN}$
 $F_y = -F\sin 0 = -5\sin 30^\circ = -2.5 \text{ KN}$
 \therefore $F_x = -4.33 \text{ KN}$
 $F_y = -2.5 \text{ KN}$



$$F_{2} = \frac{F_{2} + F_{2}}{F_{2}} = \frac{F_{2}$$

08 OD. Resolve the force of 12 KN in two directions at 30° and 40° on either side of it. Solution: - $F = \frac{40^{\circ}}{F} = 12 \text{ KN}$ $\frac{\text{Given: F = 12 KN}}{\alpha = 30^{\circ}}$ $\beta = 40^{\circ}$ Find : F, and F. We know that $F_1 = \frac{Fsin\beta}{sin(\alpha+\beta)}$: $F_1 = \frac{12 \sin 40^{\circ}}{\sin (30^{\circ} + 40^{\circ})}$: F1 = 8.21 KN and $F_2 = \frac{Fsing}{sin(\alpha + \beta)}$ $F_2 = \frac{12 \sin 30^\circ}{\sin (20^\circ + 40^\circ)}$:. F2 = 6.38 KN $F_1 \text{ along } 30^\circ = 8.21 \text{ kN}$ $F_2 \text{ along } 40^\circ = 6.38 \text{ kN}$

$$\begin{array}{c} \textcircledleft{matrix} P_{1} = \frac{p_{1}}{p_{2}} \\ \hline p_{1} + p_{2} + p_{2} \\ \hline p_{2} + p_{3} + p_{4} + p_{4} \\ \hline p_{2} + p_{4} + p_{4} \\ \hline p_{1} + p_{4$$

10 D. what are the components of GON force acting horizontal, in two directions on either side bat an angle 30° each? Solution:-F= 60N Given: F=60N. Find: F, and F2 >F We know that $F_{1} = \frac{F \sin \beta}{\sin (\alpha + \beta)}$ $F_{2} = \frac{60 \sin 30^{\circ}}{\sin (30^{\circ} + 30^{\circ})}$ $F_{2} = \frac{60 \sin 30^{\circ}}{\sin (30^{\circ} + 30^{\circ})}$ $F_{2} = \frac{60 \sin 30^{\circ}}{\sin 60^{\circ}}$ $F_{2} = \frac{60 \sin 30^{\circ}}{\sin 60^{\circ}}$ F, along 30° = 34.64 N Ans F, along 30° = 34.64 N



The resultant of two forces in a plane is
800 N at 50° with X-anis · one force is
160 N at 30° with X-anis · Determine the
misting force and its inclination ·
Solution:-
Given:- F = R = 800 N
F₁ = 160 N
Angle between F and X-anie = 30°
Angle between F and X-anie = 30°
Angle between F and X-anie = 30°
Find:- Angle between F and F₂ =
$$\beta$$
 ·
and Value of F₂.
We know that,
F₁ = $\frac{F \sin \beta}{\sin (\alpha + \beta)}$
: 160 $= \frac{800 \sin \beta}{\sin (30' + \beta)}$
: 160 $[30' + \beta] = 800 \sin \beta$
: 160 $[30' + \beta] = 800 \sin \beta$
: 160 $[5in 30^{\circ} \cos \beta + 0.866 \sin \beta] = 800 \sin \beta$
: 160 $(0.5 \cos \beta + 0.866 \sin \beta) = 800 \sin \beta$
: 160 $(0.5 \cos \beta + 0.866 \sin \beta) = 800 \sin \beta$
: 80 $\cos \beta + 138 \cdot 56 \sin \beta = 800 \sin \beta$
: 80 $\cos \beta = 561.49 \sin \beta$
: $5in \frac{\beta}{\cos \beta} = \frac{.80}{.661.49} = 0.121$

1.1

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:
$$\tan \beta = p \cdot 121$$

: $\beta = +an^{1}(0 \cdot 121)$
: $\beta = 6 \cdot 89^{\circ}$

We know that,

$$F_2 = \frac{F \sin \alpha}{\sin (\alpha + \beta)}$$

 $\therefore F_2 = \frac{800 \sin 30^{\circ}}{\sin (30^{\circ} + 6.89^{\circ})}$
 $\therefore F_2 = \frac{800 \times 0.5}{\sin 36.89^{\circ}}$
 $\therefore F_2 = \frac{400}{0.6} = 6666.67 \text{ N}$
 $F_2 = 666.67 \text{ N}$ and $\beta = 6.89^{\circ}$ Ans

• unit of stress is also denoted by Kilopascal(Kpa)
• Megapascal (MPa) and Gegapascal (Gpa)
1 Kpa =
$$10^3$$
 pa = 10^3 N/m2
1 Mpa = 10^6 Pa = 10^6 N/m2 = $\frac{10^6}{10^6}$ N/mm2 = 1 N/mm2
1 GPa = 10^9 Pa = 10^9 N/m2 = $\frac{10^9}{10^6}$ N/mm2 = 10^3 N/mm2 = 1 KN/mm2
Types of stress:

() Tensile stress: - when two equal and opposite tensile force applied to a body tend to elongate it, the body is said to be under tension and the stress induced in it is called as tensile stress.

$$P \leftarrow ---- P \rightarrow P$$

Ocompressive stress! - when two equal and opposite posseds compressive forces applied to a body tend to shooten it, the body is said to be under compression and the stress induced in it is called compressive stress.



produced in member due to shear force is called as shear strain. Hese ABCD is a cube. Siete of cube = L AB Face is fixed. NON, $\tan \phi = \frac{DD'}{AD} = \frac{X}{L}$ $\Rightarrow is very small angle \cdot [tan \phi \approx \phi]$ Here, $\phi = shear strain$ X = shear deformation .L = cube side length.

* HOOK'S LAW It States "when a material is loaded within its elastic limit, the stress produced is directly proportional to the strain'

The ratio of stress and strain which is a constant within the elastic limit is Called modulus of elasticity: Modulus of elasticity is denoted by 'E'. $\boxed{\bigcirc}_{e} = E \quad (From equation(i))$ where, $\sigma = stress$ e = strainE = Modulus of elasticity.

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Elastic limit (B) :-

Elastic limit is the maximum stress a moterial can withstand before the permanent detormation.

Upper yield point: The load at which the Sudden drop occurs is known as the upper yield point.

Lower yield point: - It is a point at which minimum load required to maintain the plastic behavior of material.

Yield point: - It is the maximum stress at which the material is directly deformed without considerable increase in load.

Ultimate load point :- it is defined as the -highest load that the material can sustain before failure.

OS, It is defined as the maximum point on the stress - strain curve of the material.

Breaking point (F): - It is defined - as the the load point in Which the material Where fracture of material takes place.







Endurance Limit :-

Endurance limit is the stress level below Which an infinite number of loading cycles can be applied to a material without Causing fatigue failure.

stress Concentration: - It is a location in an object where the stress is Segnificantly greater than the surrounding





Stress Concentration Factor = Manimum Storess (k.) - Average storess (k_t)

Factor of safety: - The ratio of ultimate stress and the working stress for a material is called factor of Safety.

Concept of Temperature stresses :-

remperature stresses and strains of uniform and composite sections

If the temperature of a body is lowered or raised its dimensions will decrease or increase Coorespondingly. If these changes, however, are checked the stresses thus developed in the body are Called temperature stresses and corresponding Strains are Called temperature strains. Let, L= Length of a bar of uniform crosst, = initial temperature of the bar t2 = final temperature of the bar,

X = Co-efficient of linear expansion

The extension in the bar due to sise in temperature will be-

 $SL = A(t_2 - t_1)L$

If this elongation in the bar is prevented by some enternal force or by fixing the bar ends, the temperature strain thus produced will be given by



Temperature Strain, et = a(t_-t_) [compressive]

NOW, Temperature stress developed, of = a (t_2-t_1) * E Komp If, however, the temperature of the bar is lowered, the temperature strain and stress Will be tensile in nature.

Q. A hollow circuler steel tube is 1000 mm in length. It is sigidly fixed at its ends at 80°C. If the temperature of the tube is lowered to 40°c, determine the magnitude and the nature of stresses developed. Take E=2×105 N/mm2 and X=12×10 %. Solution: - L=1000 mm, t;= 80°c, t= 40°c

· Temperature stress, 6= a (t2-ti)E = 12×106× (40-80) × 2×105 = - 96 N/mm2 (compressive) 6t = 96 N/mm2 (Tensile) Ans



1. A bar 500 mm long and 22 mm in diameter is elong-
ated by 1.2 mm under the effect of axial pull of
105 KN. Calculate the intensities of strees, strain
and the modulus of elasticity of the bar.
Given. L = 500 mm, d = 22 mm,
$$SL = 1.2 \text{ mm}$$
, $P = 105 \text{ KH} =$
We have to find: (i) G , (ii) e , (iii) E
 105 km , $P = \frac{P}{\pi d^2} = \frac{105 \times 10^3}{\frac{T}{4} \times (22)^2} = 276.22 \text{ N/mm}^2$
(ii) Strain, $e = \frac{SL}{L} = \frac{1\cdot 2}{500} = 0.0024$
(iii) Modulus of elasticity, $E = \frac{G}{E} = \frac{276 \cdot 22}{0.0024} = 115031 \cdot 674 \text{ Jmm}^2$
Read of 6 kN is to be saised with the help
of steel calle. Find the minimum diameter of steel
Calle if stress is not to exceed 100 N/mm^2.
Soll: - Given, load, $P = 6 \text{ KN} = 6 \times 10^3 \text{ N}$
Stress, $\sigma = 110 \text{ N/mm}^2$
We have to find: Diameter, $d = \frac{9}{4}$
We Know that stress $= \frac{\log d}{4\pi ea}$
or, $S = \frac{P}{4}$
 $M = \frac{10 \times 10^3}{\frac{T}{4} \times d^2}$
or $d^2 = \frac{6 \times 10^3}{\frac{T}{4} \times d^2}$

Q3 A rod having diameter 20 mm is subjected to an axial pull of 60 KN. The Length of the member is 2 meters. If E=2×105 N/mm2, find the deformation of the rod. <u>Solh</u>: - Given, d=20mm, P=60KN=60×10³N L=2m=2×103mm, E=2×105N/mm2 We have to find: - deformatio = EL = ? we know that SL = PL = 60×10³×2×10³ Tr * (20) 2 × 2×105 8L = 1.91 mm Ans 9.4 A 12 mm diameter M.S. bar when tested for Single Shear carries a load of 8.16 KN. Determine the shear stress induced. Soln: - Given, d= 12mm, P=8.16 KN=8.16×103N We have to find: - Shear stress, T=? We know that, the selation for single shear as Shear stress, T = Shear Load (Shear force) Area Subjected to shear $T = \frac{P}{\frac{2}{3}d^{2}}$ $= \frac{8.16 \times 10^{3}}{\frac{2}{3} \times (12)^{2}}$ ". T = 72.154 N/mm Ans



Q-5 A 8 mm diameter circuler pin in double shear Carries a force of 10 KN. Determine the stores induced. Solution: - Given, d= 8mm, P=10KN=10×103 N we have to find: - stress = T = ? we know that the double Shear stress where area subjected to shear is Double Shear Stress, T = Shear force Area Subjected to Shear

τ	11	PA				÷	
	11	10×	103	_			
	2×	4×(8)-	NIT	m	/ .	Ans
τ	=	99.2	13				

Deformation of a body subjected to Arial bods · principle of Superposition: - When a number of forces are acting on a body, the resulting Strain will be the algebraic sum of strains of the individual sections.

Q. A bar of uniform cross sectional area 100 mm2 , is subjected to the forces as shown in fig. Calculate the change in the length of the bar. Take E = 2 × 105 N/mm2.





(13)
Soln: - Given:
$$A = 100 \text{ mm}^2$$
, $E = 2 \times 10^5 \text{ N/mm}^2$
The free body diagrams for the sections AB.Bcd
CD are shown.

 $A^{+} \bigcirc B^{+} \otimes B^{+}$

9. In order to evaluate various mechanical properties,
a steel specimen of 12.5 mm diameter and 62.5
mm gauge was tested in a standard tension
test. Following observations were smade during
the test:
yield load = 40 KN, Maximum load = 71.5 KN,
Fracture Load = 50.5 KN, Gauge length of fracture=79.5m
Strain at load of 20 KN = 7.75 x/0⁴.
Determine @ yield point stress, (b) ultimate
tensile strength, © percentage elongation.
@ Modulus of elasticity @ fracture stress
Solh: - Original area of Cross-section =
$$T d^2$$

(A)
 $\therefore A = T_{1} x (12.5 x 10^3)$
 $A = 1.227 x 10^4 m^2$
@ yield point stress, $Gy = \frac{Load}{4}$ at lower yield point
 $original area
 $= \frac{40 \times 10^3}{1.227 \times 16^4} = 32.595 \times 10^5 N/m^2$
B Ultimate tensile strength = Maximum Load
 $= \frac{71.5 \times 10^3}{1.227 \times 10^5}$
(C) percentage elongation = $\frac{10.5 \times 10^3}{1.227 \times 10^5}$$



Percentage length =
$$\frac{79.5-62.5}{62.5} \neq 100$$

= 27.2%
Modulus of clasticity (E)
Stress at $20 \text{ KN} = \frac{20 \times 10^3}{1.227 \times 10^4} = 162.97 \times 10^6 \text{ N/m}2$
Modulus of clasticity, E= $\frac{\text{Stocess at } 20 \text{ KN}}{\text{Stsain at } 20 \text{ KN}}$
= $\frac{162.97 \times 10^6}{7.75 \times 10^4}$
= $2.1 \times 10^{11} \text{ N/m}2$
 Θ Fracture stress = $\frac{\text{Fracture lead}}{0 \text{ siginal area}}$

heral ... i rant sainta hout, ja nj

- + I brisse

$$= \frac{50.5 \times 10^{3}}{1.227 \times 10^{-4}}$$

= 411.5 × 10⁶ N/m²



Q. For a certain material, the modulus of elasticity is 2.8 times its bulk modulus. Calculate the poisson's ratio. Also Calculate the ratio of modulus of elasticity to modulus of -rigidity. Soln: - Given, E=2.8K We have to find: (i) M, (ii) E/G We know that, R= 3K(1-2M) or, 2.8K = 3K (1-2H) $0^{-6}, 1-2\mu = \frac{2.8}{2} = 0.93$ or 2µ=1-0.93 = 0.07 or H= 10.07 = 0.035 Ms

We know that
$$E = 2G(1+\mu)$$

or, $\frac{E}{G} = 2(1+\mu) = 2(1+0.035)$
or, $\frac{E}{G} = 2\pi 1.035$
 $\therefore = \frac{E}{G} = 2.07$ Ams



9. A bar of 30 mm diameter is subjected to a pull
of 60 kN. The measured extension on gauge length
of 200 mm-is 0.03 mm - and the change in
diameter is 0.0039 mm. Calculate the poisson's
ratio and modulus of elasticity
Soln:-
Given, d= 30mm, p=60 KN=60×10³N, L=200 mm,
$$\delta L = 0.09 \text{ mm}$$
, $\delta d = 0.0039$.
We have to find:- μ and E
Linear strain, $e = \frac{\delta L}{L} = \frac{0.09}{200} = 0.00045$
Lateral Strain = $\frac{\delta d}{d} = \frac{0.0039}{30} = 0.00013$
Poisson's ratio, $\mu = \frac{Lateral Strain}{Linears Strain}$
 $= \frac{6.00013}{0.00045}$
 $\therefore \mu = 0.29$
We know $z E = \frac{Strass}{Strain} = \frac{S}{E} = \frac{P/A}{\delta VL} = \frac{PL}{A\delta L}$
or, $E = \frac{60 \times 10^3 \times 200}{\frac{T}{4} \times (30)^2 \times 0.07}$

9: For a given material, young's Modulus is 1×10 N/mm²
and modulus of rigidity 0.4×10⁵ N/mm². Find
the bulk modulue and lateral contraction of a
round bar of 50 mm diameter and 2.5 m
long, When Stretched 2.5 mm. Take poisson's
ratio as 0.25.
Soln:-
Given, E= 1×10 N/mm², G=0.4×10 N/mm³,
d=50 mm, L=2.5 m=2.5×10³ mm,
SL=2.5 mm, µ= 0.25
We have to find:- K and 8d.
We know that E = 3×(1-2µ)
r, 1×10⁵ = 3×K(1-2×0.35)=3×0.5 = 1.5K
of K =
$$\frac{10^{5}}{1.5} = 0.67×10^{5} N/mm^{2}$$

 $\mu = \frac{Lateral Strain}{Linear Strain} = \frac{Lateral Strain}{2.5/2.5×10^{3}}$
or, Lateral Strain = $0.25 \times \frac{2.5}{2.5×10^{3}} = 0.00025$
or Sd = 0.00025×50
 $r Sd = 0.00025 \times 50$
 $r Sd = 0.00025 \times 50$
 $r Sd = 0.0125 mm Ams$



⇒ The distance between the geometric anis of the body and the point of loading is called an eccentoic limit or limit of eccutricity. > It is denoted by 'e'.

> Axial Load causes only direct stress whereas an eccentric load causes direct as well as bending stresses.







- The loading acts at point E in a plane bisecting the thickness i.e. on x-x axis i.e. it is eccentric with respect to Y-Y axis.
- > The distance GE is called eccentricity.



Combination of direct and bending stresses

Axial load: - A load whose line of action coincides with the anis of a member is called axial load.

Axial load is also called direct load.

Eccentoic load: A load whose line of action acts does not coincides with the axis of a member is called an eccentric load.

Direct Stress and bending Stress





plan

Eccentric load at E = Direct load at G + Moment at G > The downward force p acting at the centroid G [Fig. (F)] will cause a direct \$ stress.



 $\bigcirc^{\mathfrak{c}}$

- → The remaining two forces viz. a downward eccentric force p and an upward axial force p will from a clouwise couple whose moment at the controld G will be M = Pxe. This moment acting at the centrold G will cause a bending Stress.
 - > A body subjected to an eccentric leading causes direct as well as bending stress.
 - Maximum and Minimum Stress
 - Direct stress due to eccentric load p, $\overline{D_0} = \frac{P}{A}$ Bending stress ($\overline{D_b}$) due to eccentric load p: We know that the bending stress equation i.e. flexural formula. $\frac{M}{I} = \frac{\overline{D_b}}{\overline{y}}$ $\overline{D_b} = \frac{M}{\overline{z}} \times \overline{y} = \frac{M}{(\overline{A}\overline{y})} = \frac{M}{\overline{z}}$

Where, I= M.I. of the column section about the neutral anis Y-Y = db3/12

> J = Distance of the layer from the neutral dris y-y.

Ob = Bending Stress in a layer at a distance y from the neutral axis

Z = Section modulus = y

The resultant stress at a distance y from the neutral axis y-y is given by,

Or = Direct Stress + Bending Stress

Or = So ± Sb

Manimum stress, Sman = So + Sh Minimum stress, omin = 00 - 06

Stress distribution Diagram

"> Neture of Omin depends upon the magnitudes of 50 and 56.

- ⇒ for calculating the resultant stress due to eccentric loading as shown in above Fig., three cases are possible.
- (i) If To > 56, the stress throughout the section Will be of the same nature i.e. compressive. (ii) If on = on, then also the stress throughout the section will be of the same nature ie. compressive.
- (iii) If Jo < Jb, the stress will be partly tensile and partly compressive.



The stoess distribution diagrooms for the above three cases are as shown in Fig. below.



Eccentric compressive load at E

3,



(i)







stress distribution partly tensile and partly compressive So < Sb



Candition o
tor no tension in the section
When an eccentric compressive load act and
Column, it produces direct
Stress.
> If 50>66, the resultant stress is compressive.
> If Oo = of the minimum stress is zoo and the
maximum Stress is 250 and the
Stress distribution is compressive.
→ If Oo< 66, the stress is partly compressive
and party tensile.
> A small tensile stress at the base of
a structure may develop tension cracks.
Hence, for no-tension condition, direct stress
Should be greater than or equal to bending
Stress.
00 - 06

Hence, for no-tension condition, eccentricity Should be tess than Z/A, or maximum value equal to Z/A.



A Column section 200 mm wide and 150 mm
thick is subjected to a load of 200 kN at
an eccentricity of 20 mm in a plane -
biseding the thickness. Find the maximum
and minimum intensities of stress in the
section.

$$sell''$$
 Given: $b=200$ mm,
 $d=150$ mm,
 $P=200$ kN = 200 kN = 200 kN = $\frac{1}{2}$ $\frac{$

$$\begin{split} \delta_{\rm b} &= \frac{P_{\rm c} \times e}{db^2/6} \\ &= \frac{200 \times 10^3 \times 10}{150 \times 200^2/6} \\ \delta_{\rm b} &= 4 \, N/mm^2 \\ \delta_{\rm max} &= \delta_0 + \delta_{\rm b} = 6.67 + 4 = 10.67 \, N/mm^2 \, (compressive) \\ \delta_{\rm min} &= \delta_0 - \delta_{\rm b} = 6.67 - 4 = 2.67 \, N/mm^2 \, (compressive) \\ \delta_{\rm min} &= \delta_0 - \delta_{\rm b} = 6.67 - 4 = 2.67 \, N/mm^2 \, (compressive) \\ \delta_{\rm min} &= \delta_0 - \delta_{\rm b} = 6.67 - 4 = 2.67 \, N/mm^2 \, (compressive) \\ \delta_{\rm min} &= \delta_0 - \delta_{\rm b} = 6.67 - 4 = 2.67 \, N/mm^2 \, (compressive) \\ \delta_{\rm min} &= \delta_0 - \delta_{\rm b} = 6.67 - 4 = 2.67 \, N/mm^2 \, (compressive) \\ \delta_{\rm min} &= \delta_0 - \delta_{\rm b} = 6.67 - 4 = 2.67 \, N/mm^2 \, (compressive) \\ \delta_{\rm min} &= \delta_0 - \delta_{\rm b} = 6.67 - 4 = 2.67 \, N/mm^2 \, (compressive) \\ \delta_{\rm min} &= \delta_0 - \delta_{\rm b} = 6.67 - 4 = 2.67 \, N/mm^2 \, (compressive) \\ \delta_{\rm min} &= \delta_0 - \delta_{\rm b} = 6.67 - 4 = 2.67 \, N/mm^2 \, (compressive) \\ \delta_{\rm min} &= \delta_0 - \delta_{\rm b} = 6.67 - 4 = 2.67 \, N/mm^2 \, (compressive) \\ \delta_{\rm min} &= \delta_0 - \delta_{\rm b} = 6.67 - 4 = 2.67 \, N/mm^2 \, (compressive) \\ \delta_{\rm min} &= \delta_0 - \delta_{\rm b} = 6.67 - 4 = 2.67 \, N/mm^2 \, (compressive) \\ \delta_{\rm min} &= \delta_0 - \delta_{\rm b} = 6.67 - 4 = 2.67 \, N/mm^2 \, (compressive) \\ \delta_{\rm min} &= \delta_0 - \delta_{\rm b} = 0.67 \, N/mm^2 \, (compressive) \\ \delta_{\rm min} &= \delta_0 - \delta_{\rm b} = 0.67 \, N/mm^2 \, (compressive) \\ \delta_{\rm min} &= \delta_0 - \delta_{\rm b} = 0.67 \, N/mm^2 \, (compressive) \\ \delta_{\rm min} &= \delta_0 - \delta_{\rm b} = 0.67 \, N/mm^2 \, (compressive) \\ \delta_{\rm min} &= 0.06 \, N/mm^2 \, (compressive) \\ \delta_{\rm min} &= 0.06 \, N/mm^2 \, (compressive) \\ \delta_{\rm min} &= 0.06 \, N/mm^2 \, (compressive) \\ \delta_{\rm min} &= 0.06 \, N/mm^2 \, (compressive) \\ \delta_{\rm min} &= 0.06 \, N/mm^2 \, N/mm^2 \, (compressive) \\ \delta_{\rm min} &= 0.06 \, N/mm^2 \, N/m^2 \, N/mm^2 \, N/m^2 \, N/m^$$



CH-04: Combined Stress

* Important Formulae (i) Direct stress, $\sigma_0 = \frac{\Gamma}{A}$ (ii) Bending stress, $G_b = \frac{M}{ZYY} \begin{bmatrix} if the load is eccentric \\ ZYY w.r.t. YY axis]$ Bending stress, Sb = M [if the load is eccentric Zxx w.r.t. xx axis] (iii) Oman = Oo + Ob (compressive) Omin = 00 - 06 (compressive if 00>06 and tensile if Jokof) (iv) If Jo> Jb, the stress distribution diagram is totally compressive. If So = Sh, the stress distribution diagram is totally compressive. Smax = 250 and Smin =0 If GoKOD, the stress distribution diagram is partly tensile and partly compressive. I values of 'z' (section modulus) for different -Sections: 1. For a column of sectangular sections of width 'b' and depth d'. $Z_{XX} = \frac{I_{YY}}{Y_{max}} = \frac{bd^{3}/12}{d12} = \frac{bd^{2}}{6}$ $Z_{YY} = \frac{I_{YY}}{Y_{max}} = \frac{db^{3}/12}{b/2} = \frac{db^{2}}{6}$ 2. For a column of hollow rectangular section having external dimensions Band D and internal dimensions b and d.



3. For a column of solid circular section of diameter d'. ____

4. For a column of circular section of external diameter 'D' and internal diameter · · · b

$$Z = Z_{XX} = Z_{YY} = \frac{\Gamma}{Y_{max}} = \frac{\frac{\pi D^{9}}{64} - \frac{\pi d^{9}}{64}}{\frac{D}{2}} = \frac{\pi}{32} \left(\frac{D^{4} - d^{9}}{D}\right)$$

$$X = \frac{1}{\sqrt{2}} + \frac{1}{\sqrt{2}}$$



Q.1A Sectangular column is 200 mm wide and 100 mm
thick adde thick of the ix dubjected to a load of
180 kN at an eccentricity of 100 mm in the plane
bisecting the thickness.
Draw the combined stress distribution diagram
showing their values.
Solⁿ: - Given: b = 200 mm
Thick, d = 100 mm
Thick, d = 100 mm
Find: Gnax and Gmin's?
Cosse-sectional asea of
Cotumn, A = bxd
= 200×100
A = 2×10⁴mm²
Direct stress,
$$G_0 = \frac{P}{A}$$

 $G_0 = \frac{180 \times 10^3}{2 \times 10^9}$
 $G_0 = \frac{180 \times 10^3}{2 \times 10^9}$
 $G_0 = \frac{180 \times 10^3}{2 \times 10^9}$
 $G_0 = \frac{6 Pe}{dB^2}$
 $G_0 = \frac{6 Pe}{dB^2}$
 $G_0 = \frac{6 Pe}{dB^2}$
 $G_0 = \frac{6 \times 180 \times 10^3 \times 10^9}{100 \times (200)^2} = 27 N/mm2$
 $G_0 = G_0 + 27 = 36 N/mm2(Compressive)$
 $G_0 = \frac{6 \times 180 \times 10^3 \times 10^9}{100 \times (200)^2} = 27 N/mm2$

Right short column of hollow sectangular cross-section
-has enternal dimensions 1800mm. x2400 mm and is 20
mm thick: It carries a vertical load of 500 kN
at an eccentricity of 30 mm from the geometric
anix of the section bitecting the longer side
Find Smax and Smin .
Solution: -
Given: Dutester dimensions:

$$b = 1800 - 20 - 20 = 1760 \text{ mm}$$

 $d = 2400 - 20 - 20 = 1260 \text{ mm}$
 $d = 2400 - 20 - 20 = 2360 \text{ mm}$
Cross-sectional area of
the column 3 A = 8D-bd
Eccentricity, $e = 30 \text{ mm}$
 $io ad, p = 500 \text{ KN} = 500 \text{ K$

M

direct stress,
$$G_0 = \frac{P}{A}$$

 $G_0 = \frac{500 \times 10^3}{166400} = \frac{3 N/mm^2}{(compressive)}$
Bending stress, $G_b = \frac{M}{Z_{YY}} = \frac{P \cdot P}{Z_{YY}}$
 $= \frac{500 \times 10^3 \times 30}{104685985.2}$
 $G_b = 0.14 N/mm^2$
 $G_{max} = G_0 + G_b = 3 + 0.14 = 3.14 N/mm^2 (compressive)$
 $G_{min} = G_0 - G_b = 3 - 0.14 = 2.86 N/mm^2 (compressive)$

9.4 A hollow column of rectangular section 600 mm x300 mm overall and 500 mm x 250 mm internally carries a load of 15 KN which is of the geometric aris by 100 mm in the vertical plane bisecting the thickness i.e. 300 mm side . Calculate the extreme intensities of stress induced in the section. Solution:-

<u>Given: Outer dimensions</u>: Width, B = 600mm depth, D = 300mm <u>Internal dimensions</u>:width, b = 500mm depth, d = 250mm

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Load,
$$P = 15 \text{ KN} = 15 \text{ KIO}^{3} \text{ N}$$

Eccentricity, $e = 100 \text{ mm}$.
Find: Grax and Grain:
We Know that
Smax = So + Sb
Smin = So - Sb
Direct Stress, $So = \frac{P}{A}$
Area of hollow section, $A = BD - bd$
 $A = 600 \times 300 - 500 \times 250$
 $A = 55000 \text{ mm}^{2}$
 $S_{0} = \frac{15 \times 10^{3}}{55000} = 0.27 \text{ N/mm}^{2} (\text{Compressive})$
The Load is eccentric with respect to $\gamma\gamma$ -axis.
 $S_{b} = \frac{M}{Z_{\gamma\gamma}}$
 $M = Pxe = 15 \times 10^{3} \times 100 = 15 \times 10^{5} \text{ N-mm}$
 $Z_{\gamma\gamma} = \frac{DB^{3} - dB^{3}}{6B}$
 $= \frac{300 \times (600)^{3} - 250 \times (500)^{3}}{6 \times 600}$
 $Z_{\gamma\gamma} = 9319444.44 \text{ mm}^{3}$
Bending Stress, $S_{b} = \frac{M}{Z_{\gamma\gamma}} = \frac{15 \times 10^{5}}{9319444.494} = 0.16 \text{ N/mm}^{2}$
Smax = So + S_{b} = 0.27 + 0.16 = 0.43 \text{ N/mm}^{2} (compressive)

85.4 solid circular column of diameter isomm
carries a vertical load of 50 KN at outer edge of
the column calculate Smax and Smin'
solution:
diven: diameter, d=150 mm
loads
$$p = 50 \text{ KN} = 50 \text{ xN}^3 \text{ N}$$

Etcentricity, $e = \frac{d}{2} = \frac{100}{2} = 75 \text{ mm}$
 $\frac{1}{100} \frac{1}{100} \frac{1}{100}$

96. A rectangular column 300mm wide and 200 mm this Carries an axial load of 180 KN and a clockwise moment of 2.8 KN-m in the plane bisecting 200mm Side. calculate the resultant stresses induced at the base.



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$$Z_{YY} = \frac{db^{2}}{6}$$

$$\therefore G_{b} = \frac{M}{Z_{YY}} = \frac{M}{\frac{db^{2}}{6}} = \frac{6M}{db^{2}} = \frac{6 \times 2 \cdot 8 \times 10^{6}}{200 \times (300)^{2}} = \frac{0.93 \, \text{N} | \text{mm}^{2}}{200 \times (300)^{2}} = \frac{0.93 \, \text{N} | \text{mm}^{2}}{200 \times (300)^{2}} = \frac{0.93 \, \text{N} | \text{mm}^{2}}{100 \times (300 \times (300)^{2}} = \frac{0.93 \, \text{N} | \text{mm}^{$$

2 A rectangular pier 1000 mm x 1500 mm is Subjected to a compressive load of 500 KN with an eccentricity of 250 mm along the axis bisecting 1000 mm side. Find the resultant stress intensities at the base cross-section of the pier.

Solution: -





TT

Given: width, b = 1000 mm
breadth, d = 1500 mm
Load, P = 500 KN = 500 × 10³ N
Eccentricity, e = 250 mm
Find: Smax and Smin.
We Know that
Smax = So + Sb
Smin = So - Sb
Direct stress, So =
$$\frac{P}{A}$$

Area, $A = b \times d$.
 $= 1000 \times 1500 = 15 \times 10^{5} \text{ mm}^{2}$
So = $\frac{P}{A} = \frac{500 \times 10^{3}}{15 \times 10^{5}} = \frac{1}{3} = 0.33 \text{ N/mm}^{2}$
She load is eccentric with respect to xxraxis.
Sb = $\frac{M}{2xx}$
M = Pxe = 1500 × 10³ × 250 = 125 × 10⁶ N-mm
 $Zxx = \frac{bd^{2}}{6} = \frac{1000 \times (1500)^{2}}{6} = 375 \times 10^{6} \text{ mm}^{3}$
She $\frac{M}{2xx} = \frac{125 \times 10^{6}}{6} = \frac{1}{3} = 0.33 \text{ N/mm}^{2}$

$$\begin{aligned} & \operatorname{Smax} = \operatorname{So} + \operatorname{Sb} = 0.33 \pm 0.33 = 0.66 \text{ NImm2} (compressive on face AB) \\ & \operatorname{Smin} = \operatorname{So} - \operatorname{Sb} = 0.33 - 0.33 = 0 (on face CD) \\ & \underline{\operatorname{QS}} \cdot A - \operatorname{hol}(\operatorname{Iow} Circular column having external and internal diameters of 40 cm and 30 cm respectively. Carries a vertical load of 150 kN at the outer edge of the column. Calculate the maximum and minimum intensities of stress in the section. \\ & \underline{\operatorname{Solution:}} \cdot \\ & \underline{\operatorname{Given}} \cdot \\ & \underline{\operatorname{Solution:}} \cdot \\ & \underline{\operatorname{Given}} \cdot \\ & \underline{\operatorname{Solution:}} \cdot \\ & \underline{\operatorname{Given}} \cdot \\ & \underline{\operatorname{Solution:}} \cdot \\ & \underline{\operatorname{Carries}} \cdot \\ & \underline{\operatorname{Solution:}} \\ & \underline{\operatorname{Solutio$$

$$\begin{split} & S_{0} = \frac{P}{A} = \frac{150 \times 10^{3}}{54977.87} = 2.73 \text{ N/mm}^{2} (\text{Combressive}) \\ & \text{Bending Stress, } S_{b} = \frac{M}{Z} \\ & \text{M} = P \times e = 150 \times 10^{3} \times 200 = 3 \times 10^{7} \text{ N-mm} \\ & \text{Z} = \frac{\pi}{32} \left[\frac{0^{4} - q^{4}}{D} \right] \\ & = \frac{\pi}{32} \left[\frac{400^{4} - 300^{4}}{400} \right] = \frac{\pi}{2} \\ & \text{Z} = 4295146.21 \text{ mm}^{3} \\ & S_{b} = \frac{M}{Z} = \frac{3 \times 10^{7}}{4295146.21} \\ & \text{S}_{b} = 6.98 \text{ N/mm}^{2} \\ & \text{Omax} = S_{0} + S_{b} = 2.73 + 6.98 = 9.71 \text{ N/mm}^{2} (\text{empressive}) \\ & \text{Smin} = S_{0} - S_{b} = 2.73 - 6.98 = -4.25 \text{ N/mm}^{2} \end{split}$$

Q9. A C-Clamp made up of sectangular cross Section 30×10mm as shown in figure is subjected to a force of 2.5 KN. Find the stresses induced at section AB.







<u>Given</u>: Width, b=10 mm depth, d=30 mm Load, p=2.5KN = 2.5×10³N Eccentricity, e=100 mm <u>Find</u>: Smax and Smin We Know that Smax = So + Sb



$$\begin{split} & \sigma_{min} = \sigma_0 - \sigma_b \\ & \text{Direct stress, } \sigma_0 = \frac{P}{A} \\ & \text{Cross-Sectional alea, } A = b \times d \\ & = 10 \times 30 \\ & A = 300 \text{ mm}^2 \\ \\ & \sigma_0 = \frac{P}{A} = \frac{2 \cdot 5 \times 10^3}{300} \\ \hline & \sigma_0 = 8 \cdot 33 \text{ N/mm}^2 \text{ (Tensile)} \end{split}$$

1

The load is eccentric with respect to xx axis. Bending $G_b = \frac{M}{Z_{xx}}$ $M = P \times e = 2.5 \times 10^3 \times 100$ $M = 2.5 \times 10^5 \text{ N-rowm}$ $Z_{xx} = \frac{bd^2}{6} = \frac{40 \times 30^2}{6}$ $Z_{xx} = 1500 \text{ mm}^3$ $G_b = \frac{M}{Z_{xx}} = \frac{2.5 \times 10^5}{1500}$ $G_b = 166.67 \text{ N/mm}^2$ $G_{max} = G_0 + G_b = 8.33 + 166.67 = 175 \text{ N/mm}^2 (Tensile) for face}$

Omin = 00-06 = 8.33-166.67 = -158.34 N/mm² (Compressive) on face B.

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(10) A rectangular rod of Size 50 mmx100 mm is bent into E' shape as shown in figure - and applied load of 40 KN at point A' calculate the resultant stresses developed at section XX.



given! Width, b = 100 mm depth, d = 50 mm Load, P= 40KN = 40×103 N Eccentricity, e = 300 mm Find: - Smax and Smin We Know that Smax = So + Sb Omin = Go-Gb



Direct Stress, So = 1/A Cross-sectional Area, A = bxd = 100×50 A = 5000 mm2 $\sigma_0 = \frac{P}{A} = \frac{40 \times 10^3}{5000} = \frac{8 \text{ N}[\text{mm}^2(\text{Tensile})]}{1000}$ The load is eccentric with respect to YY-anis. Bending Stores, OB = M ZXY M= Pxe = 40×103×300 $M = 12 \times 10^6 N - mm$ Section Modulus, $Z_{\gamma\gamma} = \frac{db^2}{6} = \frac{50 \times (100)^2}{6}$ ZYY = 5 x10 mm2 S = Try

$$= \frac{12 \times 10^{6}}{5 \times 10^{5}}$$

$$6_{b} = 144 \, N/mm^{2}$$

Resultant Stoles: -Omax = 00+ 01 = 8 + 144 = 152 N/mm2 (Tensile) Omin = 00-06 = 8-144 = -136 N/mm² (compressive)

B11. A mild steel tube of 50 mm external diameter and 10 mm thickness is bent in the form of hook as shown in tigure. What maximum load 'p' the hook can lift if the Stresses on the cross-section AB should not exceed 100 MPa in tension and 25 N/mm² in Compression ?



Given: -External diameter, D = 50 mm Internal diameter, of= D-2t (t=Thickness) = 50-2×10 d = 30 mmOmax = 100 MPa = 100 N/mm2 (Tensile) Omin =-25 N/mm2 (compressive)



KARDER - ERAP (De Find: - Maximum load, p=? we know that, Smax = So + Sb $G_{\text{max}} = \frac{P}{A} + \frac{M}{7}$ $G_{max} = \frac{P}{\frac{T}{T}(D^2 - d^2)} + \frac{\frac{1}{T} \times e}{\frac{T}{22}(\frac{D^4 - d^4}{T})}$ $\frac{100}{\frac{\pi}{50}} = \frac{1}{\frac{\pi}{50}} \left(\frac{50^2 - 30^2}{50^2 - 30^2}\right) + \frac{100}{\frac{\pi}{32}} \left(\frac{50^4 - 30^4}{50^4 - 30^4}\right)$ 9 521010.0 = 001 ' : P= 9.85 KN .- (1) Smin = 50- 56 $G_{min} = \frac{P}{A} - \frac{M}{2}$ $\frac{1}{1-2.5} = \frac{.P}{\frac{.P}{\sqrt{50^2-30^2}}} - \frac{.P \times 100}{\frac{.P}{\sqrt{50^4-30^4}}}$:-25 = - 0.000564 P : P = 2919.2N = 2.92KN - (2)

From equation 0 and 0, the safe load to satisfy the required stress criteria is the lesser value of 040, P = 2.92 KN/Ans


Q12. A 30mm diameter rod is kent up to torm an offset link as shown in figure. If permissible tensile stress is 80 MPa, determine the maximum value of P.



e

Solution
Given: diameter of rod, d = 30 mm
Eccentricity,
$$e = 40 + \frac{d}{2}$$

 $= 40 + \frac{30}{2}$
 $e = 55 mm$
Smax = 80 Mfa (tensile) = 80 N/mm²(tensile)
Find: Load, p .
We know that
Smax = So + Sb
 $= \frac{p}{A} + \frac{M}{Z_{XX}}$ [She load is eccentric wint.xx
 $axis$]
 $= \frac{p}{A} + \frac{p \times e}{\frac{T}{32}d^3}$



$$\frac{P}{3} = \frac{P}{\frac{\pi}{4} \cdot 30^2} + \frac{P \times 55}{\frac{\pi}{32} \times 30^3}$$

$$\frac{P}{32} = 0.022164P$$

$$\frac{P}{3609.46} = 3.6 \text{ KN} \text{ Ans}$$

0

Q13. A masonry way 6 on high , 2 m thick and 1 m wide is subjected to a horizontal wind pressure of 5 KN/m2 on 1 m face. Find the value of net stresses at base of the wall. Density of masonry is 20 KN/m3.



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Solution:-

$$\underline{Given}:-$$
 Height of masonry wall, $H = 6m$
Thickness, $t = 2m$
width, $b = 1m$
Hisizontal wind poessue, $P_1 = 51 \times 10^{3} \text{ M/m}^{2}$
Density of masonry, $P = 20 \times 10^{3} \text{ N/m}^{2}$
Density of masonry, $P = 20 \times 10^{3} \text{ N/m}^{2}$
 $\underline{Density}$ of masonry, $P = 20 \times 10^{3} \text{ N/m}^{2}$
 $\underline{Density}$ of masonry, $P = 20 \times 10^{3} \text{ N/m}^{2}$
 $\underline{Find}:- S_{max}$ and S_{min} .
 $\underline{Dweight}$ of words, $W = A \times H \times P$ ($A = cross-scational dree)$
 $= (1 \times 5) \times H \times P$
 $= 2 \times 1 \times 6 \times 20 \times 10^{3}$
 $\underline{W} = 24 \times 10^{4} \text{ N}$
 $\underline{So} = 12 \times 10^{4} \text{ N/m}^{2}$
 $\underline{So} = 12 \times 10^{4} \text{ N/m}^{2}$
 $\overline{So} = 12 \times 10^{4} \text{ N/m}^{2}$
 $\overline{So} = 12 \times 10^{4} \text{ N/m}^{2}$
 $\underline{So} = 12 \times 10^{4} \text{ N/m}^{2}$
 $\underline{So} = 12 \times 10^{4} \text{ N/m}^{2}$

e



$$P = 5 \times 10^{3} \times (146)$$

$$P = 30 \times 10^{3} \text{ N}$$

$$Moment of P about the bases
$$M = P \times \frac{H}{2}$$

$$= 30 \times 10^{3} \times \frac{6}{2}$$

$$M = 90 \times 10^{3} \text{ N-m}$$

$$M = 90 \times 10^{3} \text{ N-m}$$$$

e

Bending Mornent and Shear Force

Beam: - It is a structural member which is acted upon by a system of external loads at right angles to the axis. Point load : - A point load is one which is Considered to act at a point. Et is also called as concentrated load. Distributed 10ad: - A distributed load is one Which is distributed or spread in some manner over the length of the beam. If the spred is uniform it is said to be uniformly distributed load and is abbreviated as U.D.L. If the spread is not at uniform rate, it is said to be non-uniformly distributed load. Triangular and trapezium distributed loadsjunder this category.

& Classification of beams (i) Cantilever beam: - A cantilever beam is a beam whose one end is fixed and the other end free.



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2. Simply (or freely) supported bearn :- A beam

which ends freely rest on walls or Columns or Knife edges is Called as Simply supported beam.



3. Overhanging beam :- If the end portion of the beam entends beyond the support, it is called as an overhanging beam.



4. Fixed beam :- A beam whose both ends are rigidly fixed in Walls or columns, it is called as fixed beam.



5. Continuous beam: - A beam which has more than two supports, it is called as Continuous beam.



Here A and B are end Supports, where as ic and D are intermediate Supports.



Types of loads

() point load: - A load acting at a point on the beam is Known as point load. It is also called as contentrated load.



(2) Uniformly distributed load (U.d.l.): - A load which is spread up uniformly on the beam is known as uniformly distributed load. Apromotion W/unit length L____

Here w/unit length is called as intensity of u.d.l. (3) Uniformly varying Load: - A load which is Spread up in a non-uniform manner i.e. intensity of load changes continuously but the rate of change is uniform on each unit length, then it is called a uniformly Varying Load and is written as u.v.l.



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wijunit length W2/ Unit length K W/unit Length *B A Trapezoidal load Triangular load



Reactions of Simply Supported Beams

Case I :- A Simply supported beam of Span 'L' Carefying point load 'w' as shown in fig.



As there is no horizontal force acting on the beam. : 2Fx = 0

NOW Z FY = O [Assuming upward forces positive and downward forces negative]

$$\therefore RA + RB = W = 0$$
(i)

Moment about A is zero-i.e. ZM=0

RAXO+WXL - RBXL = 0 [Taking clockwise moment positive and anticlournise moment negative] . WL = RBL $\therefore W_2 = RB$ -(11) \therefore RB = $\frac{W}{2}$ Substituting the value of Ro in egn (i), we get $RA + \frac{W}{2} = W$ RA = WZ



C <u>Case-II</u>: A Simply supported beam of span'L' Carojing U.d.L. w/unit length over the entire span as shown in fig. w/ unit length April B RA RA we have to find bears reactions Ra and Rs. As there is no horizontal force acting on the bearon: : EFx = 0 At equilibrium, 2Fr =0 · RA + RB - WXL = 0 i \therefore RA + RB = WLMoment about point A is zero. i.e. <= MA=0 Tooking Clockinse :. RAXO+WLX = - RBXL = 0 moment positive Lanticloukinse moment negative] : WLZ = RBL $\therefore \frac{\omega L}{2} = RB$ しう $R_B = \frac{\omega L}{2}$ substituting the value of RB in equis, we get. RA+WL = DL $\therefore RA = \frac{\omega L}{2}$



a

$$R_{A} = W_{D} \qquad \begin{pmatrix} a+b=L \\ b=L-a \end{pmatrix}$$

& Reactions of Countilever beam

Case I: - A Cantilever beam of span L Carrying a point load 'w' at its free end as Shown in fig.



$$\sum F_Y = 0$$

$$R_A - W = 0$$

$$R_A = W$$

Case II: A Cantilever beam of span 'L' carrying a u.d.l. w/unit length over the entire Span as shown in Fig. A former w/whit length $\Sigma F_{y} = 0$:. RA-WL=D

$$RA = WL$$

UI a

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Shear force :- Shear force at any cross-section of the keam is the algebraic som of all vertical forces on the beam acting on the right or left side of the section.

Sign convention for shear force :-



· An upward force to the left of the Section and downward force to the right of the section is taken as positive and its vice-versa is taken as negative.



Bes

6-Bending Moment: - Bending moment at any cross section of the beam is the algebraic sum of the moments of all the forces acting on the right or left side of the section. sign convention for Bending Moment:-(i) M_{1} X_{1} M_{1} $= 1 \le 0.83$ $1 \le 0.83$ 1Moment = positive Martin = Sagging $M = \frac{1}{x} = \frac{1}{Hogging}$ M = Mogging Moment = Negative Moment = Negative Moment = Negative Moment = Negative(ii) Note:-(i) If a clockwise bending moment is acting on the left hand side of the section and anticlockwise bending moment on the right hand Side of the Section, the bending moment on that section is Said to be positive. (i) If an anticlockwise bending moment

is acting on the left hand side of the section and a clockwise bending moment is acting on the right hand side section, then the bending moment of that section is said to be negative.

Relation between shear force and Rate of Loading

The sate of change of shear force with respect to the distance is equal to the intensity of loading.

$$\frac{dF}{dx} = \omega$$

Relation between bending moment and shear force. The vate of change of bending moment at any section is equal to the shear force at that section.

$$\frac{dM}{dx} = F$$

<u>Note</u>: If F=0, $\frac{dM}{dn}=0$, it means the bending moment will be maximum. The point, at which Shear force is zero or shear force changes the sign from positive to negative, is a point of maximum bending moment.



2

The point of Contraflexure

The bending moments of opposite nature always produce curvatures of beam in opposite directions In a beam if the bending moment changes sign at a point, the point itself having Zero bending moment, the beam changes Curvature at this point of zero bending moment and this point is called the foint of contraflexure. The point of contraflenure is also called the point of inflexion or a visitual thinge. # Important points to draw shear force diagram (S.F.D.) and bending Moment diagram (B.M.D.) The following points should be kept in mind while drawing S.F.D. and B.M.D. (1) Base of S.F.D. and B.M.D is equal to the span of (i) positive values of S.F. and B.M. are plotted above the base line and negative values below the base line. (iii) The values of S.F. and B.M. must be calculated at all critical points and written near the respective ordinates. Such critical points are a point where u.d.l. Starts and ends, a point where the concentrated load acts on the begon, a point where s.F. changes its sign from s.F. is Zero.)



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(iv) In case of overhanging beam, a point of Contrafferure (i.e. a point of Zero B.M.) must be located. This point can be located by equating the expression of bending moment to zero and solving it.

() The location of point of zero s.F. and the point of contraflexure must be marked toom the supports or form the ends of the beam whichever is convenient.

(VD S.F.D. is drawn below the loaded beam and G.M.D below the S.F.D.



S.F.D. and B.M.D. For Simply supported Beams

<u>Case1</u>: A Simply supported beam of span'l' carrying a central load 'w'.



Solution :-



(is simply supported beam





(ii) B.M.D.



(1)

Since the load is at the support centre, the reactions at the supports are equal.

$$RA = RB = W/2$$

Shear Force (s.F.) calculations: -

S.F. at any section between A and C is

$$F_x = R_A = \frac{N}{2}$$

S.F. at any section between C and B is

$$F_x = -R_B = -\frac{W}{M}$$

MA = MB = 0 at simply supported ends. Since S.F. changes its sign from positive to negative at point c, the maximum B.M. Will occur at c.

$$M_{max} = M_c = + \frac{W}{2} \times \frac{L}{2} = \frac{WL}{4}$$



Case 2: A simply supported beam of span'L' Carrying an eccentric point load:



(i) Simply supported beam





(11) B.M.D.

Supports reactions are:

$$R_{A} = R \frac{Wb}{L}$$
 and $R_{B} = \frac{Wa}{L}$ (the already such)
 $\frac{S \cdot F \cdot Calculations}{S \cdot F \cdot Calculations}$:
 $S \cdot F \cdot at$ any section between A and C is,
 $F_{X} = tR_{A} = \frac{Wb}{L}$
 $S \cdot F \cdot at$ any section between C and B is;
 $F_{X} = -R_{B} = -\frac{Wb}{L}$
 $\frac{B \cdot M \cdot Calculations}{D} = 0$, at Simply supported ends.
 $M_{C} = Mma_{X} = +\frac{Wb}{L} \times a = \frac{Was}{L}$

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case 3: A simply supported beam of span'L' carrying a u.d.l. w/unit length over the entire span



(i) simply supported beam



(1) S.F.D.



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O2

Support reactions:

Since the load is uniformly distoleuted over the entire length of the beam, the reactions are equal. $R_A = R_B = \frac{\omega L}{2}$ S.F. Calculations: Take a section XX at a distance x from A. $F_x = s \cdot F$ at section $XX = \frac{\omega L}{2} - \omega x$ At $A_{j} = 0$, $F_A = \frac{\omega L}{2} = +R_A$ At B, $\chi = L$, $F_B = \frac{\omega L}{2} - \frac{\omega L}{2} = -R_B$ At the centre of the beam. i.e. at c, x=42 $F_{c} = 0$

In this case, S.F.D. is an inclined straight

B. M. calculations:

B.M. at a section XX at a distance x from A is given by;- $M_X = \frac{WL}{2}rR - WR \times \frac{3}{2} = \frac{WL}{2}R - \frac{WR^2}{2}$ Since the power of x is 2, the variation of B.M. is parabolic.



At A, $\chi = 0$, $M_A = 0$

At B, Z=L , MB=0

At the centre c, the S.F. changes its sign and hence the B.M. will be maximum at G'. At C, 2= 42 Mc= Mmax = WL2



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S.F.D. and B.M.D. for Cantilever beams

Case 1: A Confilever beam carrying a point load at its free end





(i) S.F.D.



(iii) B.M.D.

Let us consider a cantilever beam AB of span'L' Caronying a point load W at its free end B. Take a section XX at a distance & from the free end B.

Fx = S.F. at section XX = + W

Thus s.f. is constant for all sections between

A and B.

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NOW, Mr= B.M. at dection XX at a distance reform =-WXX C. Since n'is measured from C, C is taken as origin. At C , x=0 i Mc=0 $AtA, x = L_1$ · MA=-WLI

"

Case 3 : A cantilever beam carrying a u.d.l. w/unit length over the entire span:



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Let us consider a cantilever bears AB of span 'L' Carrying a u.d.l. w/unit length over the entire span AB. Take a section XX at a distance x from the free end B. Fx=S.F. at Section XX=+WXL since R is measured from B, B is taken as ongin. At B, n=0 · FB= 0 AtA, X=L : FA=+WXL B.M. Calculations! Mx = B.M. at section XX = - WX M At B, n=D, . ." MB= 0 At A, n=L $M_A = -\frac{\omega L^2}{2}$

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Concept of shear force and Bending Moment



Consider a simply supported beam of span 6m carrying two point loads 10KN and 20KN at 2m and 4m from left support respectively.

$$\frac{\text{support reactions}:}{RA - 10 - 20 + RB = 0}$$

$$RA + RB = 30 \qquad (i)$$

And, $\Sigma M_{A} = 0$ $10 \times 2 + 20 \times 4 - R_{B} \times 6 = 0$ $20 + 80 - 6R_{B} = 0$ $100 - 6R_{B} = 0$ $R_{B} = \frac{100}{6} = \frac{50}{3} \text{ KN}$ $R_{B} = \frac{10}{6} = 16.67 \text{ kN}$ From O, $R_{A} = 30 - 16.67 = 13.33 \text{ KN}$

14)

Consider a section YY in position CD,
By considering the forzes acting on the left side of
dection YY, S.F. at dection YY,

$$F_Y = R_A - ID$$

 $= 13.33 - 10 = 5.23 \text{ KN}$
By considering the forzes acting on the right side of
Section YY, S.F. at section YY,
 $F_Y = 30 - R_B = 20 - 16.67 = 3.33 \text{ KN}$
Now consider a section ZZ in portion DB,
By considering the forzes acting on left side of section
 Z_2 , S.F. at dection ZZ, S.F. at dection ZZ,
 $F_Z = R_A - 10-20 = 13.33 - 30 = 16.67 \text{ KN}$
By considering the forces acting on right side of section
 Z_2 , S.F. at section ZZ, S.F. at dection ZZ,
 $F_Z = -R_B = -16.67 \text{ KN}$.
Note: It is very clear that the shear force at any
 $CORSE-Section of the beam is the algebraic Sum$

of all vertical forces acting on right side of the section. łτ To find bending moments at A, B, C and D : [+, -] $A = \frac{1}{2} \frac{1}{2}$ RA = 13.33 KN To find Me: Take a section XX at C and down the free body diagram at can shown in above fig. By considering the moments of all forces acting on the left side of c, Mc = 13.33 × 2 = 26.66 KN-m By Considering the moments of all forces acting on the right side of C, Mc = -20x2 + 16.67x2 = 26.68 KN-m.

To Find MD:

5

Take a section XX at D and draw the free body diagrass at D, as shown in fig. A 2 10KN 1X X Martin D D 2 2m-J 2m-X 2m-J Rg=13.33KN X X Rg=16.64KN

By considering the moments of all forces acting on the left side of D, MD = 13.33x4 - 10x2 = 33.32 KN-m.



6

By Considering the moments of all forces acting on the right side of D, MD = 16.67 × 2 = 33.34 KN-m

To Find MA: $R_{A} = \frac{13.33 \text{ kN}}{\text{ k}}$ Take a section XX at A as shown in Fig. By Considering all the moments of all the forces acting sight side of A. $M_{4} = -10x2 - 20x4 + 16.67x6 = 0$ Naturally, there is no force acting on heft Side of A . Hence MA=0 Side of A Hence MA=0 To Find MB:- A 2m 2m 2m X RB=16.67 KN RA = 13.33 KN Take a Section XX at B as shown infig. By considering all moments of all forces acting left side of 10, MB=13.33×6-10×4-20×2 on = 0 Naturally, there is no force acting on the sight Side of B > MB=D.

Q1 A simply supported beam of span 5m carries two point loads of 5 KH and 7 KN at 1.5m and 3.5m from the left hand support respectively. Araw s.F.D. and B.M.D. showing the important points [values.



(a) Beam





(b)2

Reactions: - EFY = 0 RA+RB-5-7=0 (1) $R_{A} + R_{B} = 12$ EMA = 0 5×1.5+7×3.5- RB×5=0 32 - 5RB=0 $R_B = \frac{32}{4} = 6.4 \text{ KN}$ Form D, RA = 5.6 KN. S.F. Calculations:-S.F. at any section between A and C, Fx = tRA = 5.6 KN S.F. at any section between c and D, Fx = 5.6-5 = 0.6 KN S.F. at any section between DandB, Fx = 5.6-5-7 = -6.4 KN B.M. Calculations:-At simply supposed ends, MA = MB = 0 By considering the forces aeting on left of C, Mc= 5.6x1.5 = 8.4 KN.m By considering the forces acting on left of D, MD = 5.6×3.5-5×2 = 9.6 KNM


Q2. A simply supported beam of span 4 m carries a u.d.l. of 2 KN/m over 400 length. Draw S.f. and B.M. diagonoms.





(b) S.F.D.



(c) B.M.D.



$$\frac{Reactions: - \Sigma F_{Y} = 0}{R_{A} + R_{B} - 2x4} = 0}$$

$$R_{A} + R_{B} = 8 \qquad \text{(i)}$$

$$\Sigma M_{A} = 0 \quad [.1] \cdot [.6]$$

$$\frac{2 \times 4 \times \frac{4}{2} - R_{B} \times 4 = 0}{R_{B} = 4 \text{ KN } 1}$$
from (i), $R_{A} = 4 \text{ KN } 1$

$$\frac{5 \cdot F \cdot ca(culations: -}{S \cdot F \cdot at any Section between A and B at a distance}{F_{X} = 4 - 2x}$$

$$At x = 0, \quad F_{A} = 4 \text{ KN } 4$$

$$At x = 2, \quad F_{E} = 0 \quad (At the centre of beam)$$
In this case, S:F.D: is on inclined straight line.
$$\frac{B \cdot M \cdot a(culations: -)}{At \text{ aimply supported burn ends} M_{B} = 0}$$

$$B \cdot M \cdot a(culations: -)$$

$$At x = 0, \quad M_{A} = 0$$

$$At x = 2, \quad M_{C} = 4 \text{ KN}$$



O.a

Q3. Draw s.F.D. and B.M.D. for the beam as shown infig.







(b) S.F.D.



(8)

$$\frac{\text{Reactions} := \Sigma F_{Y} = 0}{R_A - 2 \times 3 - 3 - 5 + R_B = 0}$$

$$R_A + R_B = 14 - (i)$$

$$\Sigma M_A = 0,$$

$$2 \times 3 \times \frac{3}{2} + 3 \times 3 + 5 \times 5 - R_B \times 9 = 0$$

$$4 3 - 7R_B = 0$$

$$R_B = \frac{43}{3} = 6 \cdot 14 \text{ KN } 3$$

$$FnmD, R_A = 14 - 6 \cdot 19 = 7 \cdot 86 \text{ KN}$$

$$\frac{5 \cdot F \cdot cal (ulation) = -}{5 \cdot F \cdot at \cdot any} \text{ section between A and c at a distance } x_1^2 \text{ from } A,$$

$$F_X = 7 \cdot 86 - 2 \times 2$$

$$At x = 0, F_A = 7 \cdot 86 \text{ KN}$$

$$At x = 3m, F_C = 7 \cdot 86 - 2 \times 3 = 1 \cdot 86 \text{ KN}$$

$$S F \cdot at any \text{ section between c and D at a distance } x_1^2 \text{ from } A,$$

$$F_X = 7 \cdot 86 - 2 \times 3 = 1 \cdot 86 \text{ KN}$$

$$S F \cdot at any \text{ section between c and D at a distance } x_1^2 \text{ from } A,$$

$$F_X = 7 \cdot 86 - 2 \times 3 = 3 \cdot 86 \text{ KN}$$

$$\frac{At x = 3}{F_C} = -1.14 \text{ KN}$$

$$\frac{At x = 5}{F_D} = -5 \cdot 14 \text{ KN}$$

$$\frac{At x = 5}{F_C} + 5 \cdot 5 - 5 \cdot 5 = -5 \cdot 14 \text{ KN}$$

$$\frac{B \cdot M \cdot Calculations :-}{At simply support ends, M_A = M_B = 0}$$

$$M_C = 7 \cdot 86 \times 3 - 2 \times 3 \times \frac{3}{2} = 14 \cdot 58 \text{ KN} \cdot m$$

$$M_B = 7 \cdot 86 \times 3 - 2 \times 3 \times 3 \cdot 5 - 3 \times 2 = 12 \cdot 38 \text{ KN} \cdot m$$

Cantilever Beam



Q1: A Cantilever beam of span 2.5 m Carries two point loads 1 KN and 3KN at 1m, 2.5 m from the fixed end. Draw S.F.D. and B.M.D.



S.F. Calculation :-S.F. at any section between Cand B, Fx = + 3 KN S.F. at any section between A and C, Fx=3+1=4KN B.M. Calculation: At the free end B, MB=0 Mc = - 3×2 = - 6 KN·m [minus sign due to clockhise moment to the night i.e. hogging] MA = -3×25-1×1 = -8.5 KN.m



8

12: Draw S.F. and B.M. diagrams for the beam Shown in Figure.



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S.F. calculations :-

S.F. at any section between A and B at a distance oc from A.

$$F_{X} = \tilde{g} - 2n$$

$$At = 0, F_{A} = 9 K N$$

$$At = 4.5, F_{B} = 0$$

$$At = \frac{4.5}{2}, F_{C} = 4.5 K N$$

B.M. at any section between A and B at a distance x from B.

$$M_{\chi} = -2\chi\chi\chi^{\frac{n}{2}}$$

At 1372=0, MB=0 At A, n=4.5, MA = -20.25 KN.m



13. Draw S.F. and B.M. diagrams for the beam shown in Fig.



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Reactions: -2Fy =0 . RA-2-3-2+2.5=0 RA = 10 KN.

S.F. Calculations:-S.F. just to the teft of B, FB = 3 KN S.F. just to the night of D, FD=3+2x2=7KN S.F. just to the left of D, FDL= 3+2x2+2=9KN S.F. just to the night of C, For= 3+2+2+2+2×2+0.5=10KN Since there is no load between A and C, 10KN remains Constant from A to C. rie. Fa = 10 KN.

B.M. calculations !-MB=0 MD = - 3×2 - 2×2×2; = -10 kNm MC = - 3×2.5 - 2×2.5×2.5 - 2×0.5 =- 1875 KNM. $M_{A} = -3 \times 4.5 - 2 \times 2.5 \times (2.5 + 2) - 2 \times 2.5 = -34.75$ KNM

0

Q.1

overhanging Beams

2222 Q1 A simply supported beam having equal overhangs on both Sides and carrying point loads is shown in Fig. Draw S.F. and B.M. diagrams.







D S.F.D.



(B.M.D.

02 Reactions:- EFY = 0 RA+RB-10-20-10=0 RA+RB = 40 -0 ZMA=0. [G+, 5] -10×1+20×2+10×5- - RBX4=0 RB = 20 KN RA = 20 KN [form(i)] S.F. Calculations :-S.F. at any section in CandA = - 10KN 5. F. at any section in A and E = -10+RA = - 10+20 = + 10 KN 5. F. at any section in Eand B = -10 + RA+20 = -10+20-20 = -10 KN S.F. at any section in Band D = -10+ RA - 20 + RA = -10+20-20+20 =+10 KN .

$$\frac{B \cdot M \cdot Calculations:}{Mc = 0}$$

$$M_{A} = -10 \times 1 = -10 \text{ KNim} (Hogging)$$

$$M_{E} = -10 \times 3 + R_{A} \times 2 = -10 \times 3 + 20 \times 2 = 10 \text{ KNm} (Sagsing)$$

$$M_{B} = -10 \times 1 = -10 \text{ KNim} (Hogging)$$

$$M_{D} = 0$$

In A simply supported beam having an overhang 232 at one side carry u.d.l. of intensity LOKN/m as shown in Fig. Draw S.F. and B.M. diagrams for the bears.



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Support reactions! -

$$\Sigma F_{Y} = 0$$

 $R_{A} + R_{B} - 50 = 0$
 $R_{A} + R_{B} = 50 - 0$
 $\Sigma M_{A} = 0, R_{B} \times 4 - 10 \times 5 \times 5 = 0$
 $R_{B} = 31.25 \text{ kN} \cdot R_{A} = 18.75 \text{ kN} \text{ (from (i))}$

S.F. Calculations .

$$F_{A} = + R_{A} = 18.75 \text{ KN}$$

$$F_{BL} = 18.75 - 10 \times 4 = -21.25 \text{ KN}$$

$$F_{BR} = 18.75 - 10 \times 4 + 31.25 = 10 \text{ KN}$$

$$F_{C} = 18.75 - 10 \times 4 + 31.25 - 10 \times 1 = 0$$

$$\frac{B\cdot M}{A} = \frac{Calculations}{2} = \frac{1}{2} + \frac{1}{2} +$$

Point of Contonflemure .
Let the point of contraflemure 'E' is at a distance x
from A.

$$M_X = 18.75 \times a - 10 \times n \times \frac{n}{2} = 0$$

 $n = 3.75 \text{ m}$ from A.

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CH:05: Bending and shear stresses

 $\mathbb{O}_{\mathcal{L}}$

ai 20 bit Junio 1 11 the dicorr Bending Moment: - Bending moment at any cross-section of the beam is the algebraic sum of the moments of all the forces acting on the right or left side of the section. 101.34000 Bending Stress: - The stresses induced to resist the bending moment are called bending stresses. shear stress: - The stresses induced to resist the Shear force are called shear stresses. It is also called shearing stresses. Neutral Aris:-4. The hand crite sections which and



233 3 12 V The fibres in the dotted Centroidal Layer are neither shortened nor elongated. This centroidal layer which do not undergo iz sydrawid any elongation or compression is called neutral layer or neutral surface. The intersection of the neutral layer with any normal cross section of a beam is Called neutral axis (No A.).

e is a sol !!

Assumptions in the theory of bending

- 1. The material of the beam is homogeneous and isotopic . i.e. the beam is made up of same material throughout and it has the same elastic properties in all the directions.
- 2. The beam is straight before boading and is of uniform cross-section throughout.
- 3. The beam material is stressed within its elastic limit and thus obeys Hooke's law.
- 4. The transverse sections which were plane before bending remain plane after banding.
- 5. The keam is subjected to pure bending.
- 6. The value of modulus of elasticity (E) is Same, for the fibres of the beam under Compression or under tension.
- .7. Each layer of the beam is free to expand or contract independently of the layer above or below it. Part Assessing the

2) - measure of the manager three internet and

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+ Equation of bending

 $\left|\frac{M}{I} = \frac{C}{\chi} = \frac{E}{R}\right|$

2⁵

Where, M = Moment of resistance I = Moment of inertia of the section about o = bending stress aluguitos sculle

& = Distance of surface from neutral azis. the start strate stabilition diagrams for asymptotical scattered E = Modulus of elasticity

R= Radius of curvature of Neutral axis

The above equation is known bending equation. It is also called Flexusal formula.

Moment of resistance:-

Moment of resistance of the beam is the moment of couple formed by the total compressive force acting at the c.g. of the compressive stress diagram and the total tensile force acting at the C.g. of the tensile stress diagram. It resists the external bending moment. In In the equilibrium condition, the moment of resistance must be equal to the enternal bending moment, i.e. Mr=M.



Bending stress distribution diagrams for symmetrical section. >1 Ock Sc= 5 Ϋ́c -101 K (b) Rectangular (d) (e) Square (2) (f)Circular I Channel Bending stress deagram. # Bending stress distribution diagrams for asymmetrical sections > 5 K 02 + 9 Ye -704 (b) (c) (d) (e) Inverted T Unsymmetrical Angle Angle (9) and the (f) T Bending Storess diagram Ar tradially 33 WE - 212 5 15 sitist having alound a framming att is most entine anti suizear a rest intel r miranil 220242 alt in primer prof. formetes said states 11 among +11. and pairies 11-1 . 0 17 to control of and the anticalities all rea to and the off of law of the the militar of - MELM -ST. Scimarn Friil rod

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Section Modulus :-

It is the ratio of moment of Inertia of the section about the newtral axis and the distance of the most extreme fibre from the newtral axis. → It is denoted ky 'z'. I allow the

→ It's S.I. unit is ma

We know that from fleaveral formula, $\frac{M}{I} = \frac{\sigma}{Y}$ $M = \sigma \left(\frac{I}{Y}\right) \cdot \frac{M}{I}$

where, Z= If is called as section modulus.

U section Modulus of rectangular section

$$Z_{XX} = \frac{bd^2}{6}$$

 $Z_{YY} = \frac{db^2}{6}$
 $Z_{YY} = \frac{db^2}{6}$
 $X < -\frac{1}{5} + \frac{1}{5} + \frac{1}{5}$

(2) Section Modulus of Solid Circular Section $\vec{Z} \times \vec{X} = Z_{YY} = \frac{\pi}{32} D^3 \qquad \vec{X} \leftarrow \vec{Y} \rightarrow \vec{X}$

3 Section Modulus of hollow circular Section

× (-

$$\dot{Z}_{XX} = Z_{YY} = \frac{\pi}{32} \left[(D^4 - d^9) \right]$$

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35



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+ Shear stress equation and the meaning of symbols used > In a simply supported beam subjected to some loading,

$$q = \frac{SAY}{Ib}$$

g = Intensity of shear stress induced in a layer at a distance y form the N.A. A = Area of beam above the layer under Consideration

- y = Distance of the c.g. of the area Considered from the neutral aris
- Ay = Moment of the area above the layer considered about the neutral 9 ris
- I = Moment of inestia of the whole cross section about the neutral axis = INA.
- b = width of the section at a distance y from the neutral anis (N.A.)





Note:-, for a rectangular section, the maximum Shear stress is 1.5 times the average Shear Stress.

1



Note: - For a circular section, the maximum shear stress is 4 times the average shear stress.

⁵

Shear stress distribution diagram for a hollow rectangular section



Cross-Section

Shear stress distribution

of charles and reade approve

M.1. of hollow sectangular section about N.A. = I= 1/(BD3-bd3)

Average shear stress = Shear Force Area la rissile provenizor $v_{av} = \frac{S}{BD - bd}$ 110.000

Maximum shear stress =

Moto in firm and mail sold in the interior a soft is show The Massie opening when the married and in



8 .:

Q. Defermine the maximum bending stress developed in a beam of ractangular cross-section 50 mm x 150 mm. When a bending moment of 600 Nom is applied about x-x-anis.

Find: 6 -> 3.2N/mik dt 150mm X Х 8C -> 3.2N/mm H 50mm - * (i) Bending stress distribution (i) Section

$$I_{xx} = \frac{bd^3}{12} = \frac{50 \times 150^3}{12} = 14062500 \text{ mm}^4$$

$$X = \frac{d}{12} = \frac{150}{12} = 75 \text{ mm}$$

We know that,
$$\frac{M}{T} = \frac{G}{Y}$$

ð

2

$$ah, \frac{600 \times 10^3}{14062500} = \frac{6}{75}$$

 $01, 6 = \frac{600 \times 10^3 \times 75}{14062500}$ 3.2 N/mm2

g. A sectangular beam of 400mm × 200mm size is of wood material. If the permissible bending Stress in wood is 2 N/mm2, calculate the moment of resistance of begros.

<u>Solh</u>:- b= 400 mm, d= 200 mm $6 = 2N/mm^2$



 $L_{XX} = \frac{bd^3}{12} = \frac{400 \times (200)^3}{12} = 26666666666.7 mm^4$ y = d = 200 = 100 mm

NOW, M = 5 T = Y

$$\frac{M}{2666666666.7} = \frac{2}{100}$$

$$M = \frac{2 \times 266666666.7}{100}$$

$$M = 5.33 \times 10^{6} \text{ N.mm}$$

$$M = 5.33 \times 10^{3} \text{ KN-rmm}$$

$$M = 5.33 \times 10^{3} \text{ KN-rmm}$$



Q. A cantilever beam of 4 m span carries a u.d.d. of 5 KNIM and permissible stress in the material of the beam is 5 N/mm². Design the section of beam if depth to width ratio is 2.

$$\frac{\$01^{n}!}{\texttt{Given}!} = 4m, \ \omega = 5 \text{KN} m, \ 6 = 5 \text{N} m^{2}, \\ d = 2b = \frac{5 \text{N} m}{2}$$



For a confilever began carrying well. over the enfire span, $M = \frac{\omega L^2}{2} = \frac{5 \times 42}{2} = 40 \text{ kNrm} = 40 \times 10^6 \text{ Nrmm}$ $I_{XX} = \frac{bd^3}{12} = \frac{bx(2b)^3}{12} = \frac{8b'}{12} = \frac{2b'}{2}$ y = 25 = 25 = 6 Using bending stores equation, M= y or, $\frac{40\times10^{6}}{25} = \frac{5}{5}$ or, $b^3 = 12 \times 10^6$ $b = 228.94 mm \approx 230 mm 1/ms$ d = 2b = 27230 = 460 mm /ms

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9. Find the section modulus of a reetangular section \ 200 mmx 500 mm about N-axis.

<u>Solh:</u> - Given: b= 200 mm, d= 500 mm

Find : ZXX

 $\begin{aligned} I_{XX} &= \frac{bd^{3}}{12} , \quad \forall max = \frac{d}{2} \\ Z_{XX} &= \frac{T_{XY}}{Jmax} = \frac{bd^{3}/12}{d/2} = \frac{bd^{2}}{6} = \frac{200 \times (500)^{2}}{6} \\ \hline Z_{XX} &= 8.33 \times 10^{6} mm^{3} \int \frac{Jmx}{d/2} \end{aligned}$

Q. A simply supported bears of span 3m Carries a wedel. of 1000 N/m throughout the span. Calculate the modulus of section if the permissible bending stress for the material is 9 MPa.

Roll: - Given: L= g.M., W = 1000 N/m, 5=9 MPR=9 N/m. Find: - Z for a simply supprofed bears carrieging u.d.l. over the entire span,

$$Mmax = \frac{U0L^2}{8} = \frac{1000 \times 3^2}{8} = 1.125 \times 10^6 N.m$$

= 1.125 × 10⁶ N.mm

bring the bending stress equation,

$$\frac{M}{T} = \frac{G}{3}$$

or, $\frac{1 \cdot 125 \times 10^{6}}{T} = \frac{.9}{3}$
or $\frac{T}{3} = \frac{1 \cdot 125 \times 10^{6}}{.9} = 0 \cdot 125 \times 10^{6} \text{ mm}^{3}$
or $Z = \frac{1}{.9} = 0 \cdot 125 \times 10^{6} \text{ mm}^{3}$ Ams

Q. A ciscular beam of 120 mm diameter is Simply supported over a span of 10m and carries a u.d.l. of 1000 N/m. Find the maximum bending stress produced. <u>soln</u>:- <u>Given</u>: diameter, d= 120 mm Length of beam, L = 10m = 10×10 mm U:d.l., W = 1000 N m = 1000 N = 1 N mmFind :- Maximum bending stress, 5 = ? -XOK Cross-Section Bending stress diagram S.S. beam

For a simply supported beam carrying u.d.l. ever the span of beam, Bending moment, $M_{max} = \frac{\omega L^2}{8}$ $= 1 \times (0 \times 10^3)^2 = 125 \times 10^{5} N - mm$

Moment of Inertia of a circular cross-section,

$$I = \frac{\pi}{64} d^4 = \frac{\pi}{64} * (120)^4 = 10178760.2 \text{ mm}^4$$

 $f = \frac{4}{2} = \frac{120}{2} = 60 \text{ mm}$
Using bending equation, $\frac{M}{T} = \frac{5}{7}$
 $h = \frac{125 \times 10^5}{10178760.2} = \frac{5}{60} \implies 5 = 73.68 \text{ N/mm}^2 \text{ Ans}$

01

At cantilever beam of span L carrying a point load W, Bending Moment, M = WL = Wx6.5x10³ Moment of infortia, I = $\frac{bd^3}{12} = \frac{400 \times (700)^3}{12} = 1.143 \times 10^{10} \text{ mm}^3$ $J = d_2 = \frac{700}{2} = 350 \text{ mm}$. Using banding equation, $\frac{M}{T} = \frac{5}{T}$ or, $\frac{W \times 6.5 \times 10^3}{1.143 \times 10^{10}} = \frac{280}{350}$ or, W = 1406769.23 N Ams

02

Q3
Q. Find the bending stress at 25 mm below the
typ edge of rectangular section somm wide
and 200 mm deep, if maximum bending
mement is 4 kN·m.
Solution: - Given: - width, b = 80 mm
deth, d = 200 pm

$$deth, d = 200 pm$$

 $deth, d = 200 pm
 $deth, d = 200 pm$
 $deth, d = 200 pm$
 $deth, d = 200 pm
 $deth, d = 200 pm$
 $deth, d = 100 pm$
 $deth, d = 200 pm$$$

Q. A steel strip 40 mm wide and 6 mm thick
is subjected to end couples 20 N·m · Find
the vadius of curvature of the bent up
strip, if
$$E = 2 \times 10^{5}$$
 MPa ·
solution:- Given: width, $B = 40$ mm
Thick, $d = 6$ mm
couple of Bending Moment, $M = 20$ N/m = 20×10^{3} N·mm
 $E = 2 \times 10^{5}$ M/a = 2×10^{5} N/mm²
Find: Radius of curvature, $R = ?$
Wing bending equation,
 $\frac{M}{I} = \frac{E}{R}$
of $\frac{20 \times 10^{3}}{12} = \frac{2 \times 10^{5}}{R}$
of $R = 7200$ mm = $7.2m$ Ams



oy

Q. A bearn having modulus of elasticity of 2.8×105 N/mm² is bent with radius of curvature of 28 m under the effect of bending moment of 5000 N.mm. Calculate the moment of inertia of the cooss-section of the beam. <u>Solution:</u>- Given:- E = 2.8×10⁵N/mm² R = 28m = 28×10³mm M = 5000 N-mm Find:-, Moment of inertia, I. using bending equation, M = ER $0\lambda, \frac{5000}{I} = \frac{2.8 \times 10^{5}}{28 \times 10^{3}}$ 01 I = 500 mm 4 Ams



05

CH-8: Finite Element Method [FEM]

Introduction to Finite Element Methods (FEM):

The **Finite Element Method (FEM)** is a powerful computational technique used to solve complex problems in engineering and physics, particularly those involving structures, fluids, heat transfer, and electromagnetism. It is widely applied in various fields such as mechanical engineering, civil engineering, aerospace engineering, and biomedical engineering.

FEM allows for the approximation of solutions to partial differential equations (PDEs) by breaking down complex problems into simpler, smaller components.

FEM is a method for solving partial differential equations (PDEs) that arise from physical phenomena, such as heat conduction, fluid flow, and structural deformation. It involves breaking down a large, complex system into smaller, simpler parts called "finite elements." These elements are connected at points called "nodes." By approximating the solution within each element and assembling the solutions for all elements, FEM can provide an approximate solution to the original problem.

Methods employed in FEM- Steps in FEM

1. Problem Definition

FEM is typically used to solve boundary value problems, which involve finding the unknown behavior (e.g., displacement, temperature, or stress) of system under given conditions, subject to certain constraints. These problems can be described by:

- **Partial Differential Equations (PDEs):** These govern the behavior of physical systems, such as heat conduction, fluid flow, or structural deformations.
- **Boundary Conditions:** Conditions that specify the behavior of the system at its boundaries, like fixed supports or specified temperatures.
- Initial Conditions (if time-dependent): Describes the initial state of the system at the start of the analysis.

2. Discretization of the Domain

In FEM, the first step is to **discretize** the physical domain (the structure or material of interest). The domain is divided into small, simple shapes called **finite elements**, which can be triangles, quadrilaterals, tetrahedra, or hexahedra depending on the problem's dimensionality and geometry. These elements are connected at points known as **nodes**.

- Element: A small, simple subdomain that can be solved independently.
- Node: The points that define the corners of each element and where the solution (e.g., displacement, temperature) is computed.
- Mesh: The entire collection of elements and nodes that form the discretized domain.

3. Formulation of the Problem

Each element is modeled mathematically using a set of **shape functions** that interpolate the solution within the element. The solution is usually approximated by expressing the unknown variable (e.g., displacement or temperature) as a linear combination of shape functions.

- Shape Functions: These define how the solution behaves within each element.
- **Element Stiffness Matrix:** For structural problems, the stiffness matrix describes the relationship between the forces applied to the element and the displacements that result from those forces.
- **Global System of Equations:** The system of equations for all elements is assembled into a large system, typically written as:

 $[K]{u}={F}$ Where,

[K] is the global stiffness matrix,

- $\{u\}$ is the vector of unknown displacements, and
- $\{F\}$ is the vector of external forces or loads applied to the system.

4. Assembly of the Global System

The contribution of each element's stiffness matrix and force vector is assembled into a global system of equations. This involves summing up the local stiffness matrices and force vectors from all elements, taking into account how the elements share nodes.

5. Solution of the System

Once the global system of equations is established, it is typically solved using numerical techniques such as direct solvers (e.g., Gaussian elimination) or iterative methods (e.g., Conjugate Gradient). The result is a set of approximate values for the unknowns at the nodes (e.g., displacements, temperatures, etc.).

6. Post-Processing

After solving for the unknowns, the results are analyzed and interpreted. This might involve:

- Visualization: Graphical representations such as deformed shapes, stress distributions, or temperature gradients.
- Validation: Comparing the results with experimental data or known analytical solutions to ensure accuracy.
- **Refinement:** Refining the mesh (i.e., making the elements smaller) to improve accuracy if necessary.

Finite Element Method (FEM) - Concept of Discontinuity

FEM is a powerful numerical method used for solving complex engineering problems, especially those involving structures, fluids, and heat transfer. It divides a large problem into smaller, simpler parts called elements, which are connected at nodes. While FEM is highly versatile and effective, there are both advantages and disadvantages to using it, especially in cases involving discontinuities (such as cracks, holes, or sudden material property changes).

Advantages of FEM:

- 1. Versatility: FEM can be applied to a wide range of problems including static, dynamic, linear, and nonlinear analyses. It is used in solid mechanics, fluid dynamics, heat transfer, electromagnetic fields, and more.
- 2. **Complex Geometries**: FEM can handle complex geometries and boundary conditions, making it suitable for irregular shapes and structures.
- 3. **Discretization**: The domain of the problem is divided into smaller, manageable parts (elements), making the problem solvable.
- 4. Adaptability to Discontinuities: FEM is capable of addressing problems involving discontinuities such as cracks, holes, and material property changes by refining the mesh in those regions.
- 5. Local Refinement: In regions with high gradients (like discontinuities), FEM allows mesh refinement to capture the variations more accurately without needing to refine the entire model.
- 6. Accurate Results: The method provides accurate solutions, especially when higher-order elements are used and the mesh is refined sufficiently in critical areas.
- 7. **Support for Nonlinear Analysis**: FEM can handle nonlinear material behavior, large deformations, and boundary conditions, which is crucial for real-world applications.

Disadvantages of FEM:

- 1. **Computational Cost**: FEM simulations, especially for large models with complex geometries or when dealing with fine meshes, can be computationally expensive and time-consuming.
- 2. **Complexity of Setup**: Setting up a FEM model requires significant expertise, particularly when handling complex boundary conditions, material properties, or nonlinear behavior.
- 3. **Mesh Dependency**: The accuracy of the solution depends heavily on the mesh quality. Poor mesh choices can lead to inaccurate results, particularly near discontinuities.
- 4. **Handling Discontinuities**: While FEM can handle discontinuities, it is challenging to represent them perfectly without introducing errors, especially in regions with sharp gradients or stress concentrations.
- 5. **Convergence Issues**: Some problems, especially those with highly nonlinear or timedependent behavior, may face convergence difficulties if not properly set up or if the mesh isn't refined enough.
- 6. **Post-Processing Requirements**: Interpretation of results requires sophisticated post-processing tools to extract meaningful engineering insights.
Limitations of FEM:

- 1. **Singularity at Discontinuities**: FEM can struggle with representing sharp discontinuities (like cracks or material interfaces) because these singularities often require very fine meshes to resolve, which can be computationally prohibitive.
- 2. **Stress Concentrations**: At points of discontinuity, stress concentrations may occur. FEM approximates these concentrations, but accurate representation often requires very dense meshes, which increases computational load.
- 3. **Material Property Changes**: Discontinuities in material properties (such as a sudden change in material composition or phase) require special handling, and errors may arise if the material interface is not modeled properly.
- 4. Fracture Mechanics: While FEM can model crack propagation, handling dynamic fracture (moving cracks or growing fractures) requires advanced techniques like cohesive zone models or extended finite element methods (XFEM), which can be complex to implement.
- 5. **Boundary Conditions**: Discontinuities at boundaries (e.g., a hole in a plate) may result in problems with boundary condition application or numerical artifacts if the boundary is not carefully defined.

Applications of FEM:

- 1. **Structural Analysis**: FEM is widely used in structural engineering to analyze stresses, strains, and deformations in buildings, bridges, and mechanical components.
- 2. **Heat Transfer**: It is used to model heat conduction, convection, and radiation, especially in complex systems with varying material properties and boundary conditions.
- 3. Fluid Dynamics: FEM is applied to solve fluid flow problems, particularly when there are changes in material properties or complex geometries.
- 4. Acoustic Analysis: FEM is used to study sound wave propagation, vibration, and noise control in various structures.
- 5. Electromagnetic Fields: FEM is used in electrical engineering to analyze fields in devices like antennas, capacitors, and magnetic materials.
- 6. **Fracture Mechanics**: FEM, especially with extensions like XFEM, is used to model crack growth and failure in materials, which is crucial in aerospace, automotive, and civil engineering.
- 7. **Biomechanics**: FEM is applied to simulate human tissues, bones, and organs under various forces for medical and prosthetic design.
- 8. **Geotechnical Engineering**: Used for soil-structure interaction problems, FEM is applied in the design of foundations, tunnels, and other geotechnical structures.

Chapter-9

<u>Finite Element Analysis</u>

Steps in Finite Element Analysis (FEA)

The general procedure for performing FEM involves the following steps:

1. **Preprocessing**:

- Define the problem (governing equations and boundary conditions).
- Discretize the domain into finite elements (mesh generation).
- Choose an appropriate element type (e.g., 1D, 2D, or 3D elements).
- Assign material properties and load conditions.
- 2. Solution:
 - Formulate the system of equations based on the weak form.
 - Assemble the global stiffness matrix.
 - Apply boundary conditions and solve the system of equations to get the unknown values (e.g., displacement, temperature).

3. Postprocessing:

- Analyze the results (e.g., visualize the displacement, stress, or temperature distribution).
- Interpret the results and check if they meet physical expectations or validate with known solutions.

The FEA process is typically broken down into several distinct phases:

1. Pre-Processing (Model Setup)

In this phase, the problem is prepared for the analysis, and it involves several key steps:

- Geometry Definition: The first step is to define the geometry of the structure or system you are analyzing. This could be a solid, shell, or beam model depending on the application.
- **Material Properties**: Define the material properties for each element in the model. This can include properties like Young's Modulus, Poisson's ratio, density, thermal conductivity, etc.
- **Meshing**: The geometry is divided into small, simple elements (e.g., tetrahedra, hexahedra, or beam elements). Meshing involves selecting the type, size, and quality of these elements.
- **Boundary Conditions and Loads**: Define the external constraints and loads acting on the system. Boundary conditions could include fixed supports, symmetry constraints, or temperature variations, while loads might be forces, pressures, thermal gradients, etc.
- Element Selection: Choose the appropriate type of finite elements (e.g., 1D, 2D, 3D, solid, shell, or beam elements) based on the nature of the problem.

2. Solution Phase

Once the model is set up, the next step is to solve the system of equations that represent the physical behavior of the structure. This phase involves:

- Assembly: The global stiffness matrix is assembled from the individual element stiffness matrices. This process typically requires knowledge of the shape functions and interpolation methods.
- Solving the System of Equations: The governing equations (often in the form of linear or nonlinear equations) are solved. For linear problems, this can be done using methods like Gaussian elimination or iterative solvers. For nonlinear problems, more advanced techniques, such as Newton-Raphson, may be required.
- **Post-Processing for Nonlinear Problems**: For nonlinear problems, an iterative process is used, and the system is solved for each time step or increment.

3. Post-Processing (Results Interpretation)

In this phase, the results of the analysis are examined and interpreted:

- **Visualization**: Results are often visualized using contour plots, displacement plots, and deformation animations to better understand the behavior of the system.
- Stress, Strain, and Deformation Analysis: The main results are stresses, strains, deformations, and other derived quantities like factor of safety, heat distribution, etc.
- Verification and Validation: Results are checked for accuracy, often by comparing them to analytical solutions (for simple cases) or experimental data.
- **Optimization**: Based on the results, design changes might be proposed to improve performance, safety, or material usage.

4. Post-Analysis Phase (Model Refinement and Reporting)

This phase typically involves refining the model and finalizing the analysis:

- **Model Refinement**: Based on the results from the initial analysis, you might refine the mesh, update the material properties, or apply more accurate boundary conditions.
- Sensitivity Analysis: Perform a sensitivity analysis to understand how changes in input parameters (like material properties or load conditions) affect the results.
- **Documentation**: Finalize the analysis by preparing reports or presentation materials that summarize the model setup, assumptions, results, and any recommendations or design improvements.

Discretization process:

Discretization is a fundamental process in the Finite Element Method (FEM), which involves dividing a continuous domain (geometry or structure) into smaller, finite parts called elements. These elements are interconnected at specific points called nodes. By discretizing the domain, the governing partial differential equations (PDEs) of the problem can be approximated using a system of algebraic equations.

Steps in the Discretization Process:

1. Geometric Domain Division:

- The first step is to break down the continuous geometry of the problem into a finite number of elements (e.g., triangles, quadrilaterals in 2D or tetrahedra, hexahedra in 3D).
- The shape, size, and number of elements depend on the complexity of the geometry and the desired accuracy.

2. Selection of Element Types:

- The type of elements used depends on the problem domain, e.g., line elements for 1D problems, triangular or quadrilateral elements for 2D, and tetrahedral or hexahedral elements for 3D problems.
- Higher-order elements can be used for increased accuracy.

3. Node Placement:

- Nodes are strategically placed at element corners, edges, or internally, depending on the type and order of the element.
- Nodes serve as the points where the solution is explicitly computed.

4. Interpolation Functions:

- Within each element, the solution is approximated using interpolation (or shape) functions that depend on nodal values.
- These functions are typically linear or polynomial, depending on the order of the element.

5. Governing Equation Approximation:

- The governing PDE is transformed into its weak or variational form, suitable for FEM application.
- The domain is discretized, and the integral equations are approximated for each element.

6. Assembly of Global System:

The local element equations (stiffness matrix, force vector, etc.) are assembled into a global system of equations using connectivity information.

7. Application of Boundary Conditions:

• Essential and natural boundary conditions are imposed on the discretized equations to ensure the solution satisfies physical constraints.

8. Solving the System:

• The resulting system of algebraic equations is solved using numerical methods to obtain approximate solutions at the nodes.

Meshing-Element Type

In Finite Element Method (FEM), **meshing** is the process of dividing a geometric model into smaller, discrete elements to solve physical problems numerically. The type of **element** chosen during meshing depends on the geometry, problem type, and required accuracy.

Below are common **element types** used in FEM:

1.1D Elements

- Applications: Beams, trusses, frames, and slender structures.
- Types:
 - **Bar/Truss Elements**: For axial forces only (e.g., tension, compression).
 - **Beam Elements**: For axial, bending, and shear forces.
- **Shape**: Straight or curved line segments.

2. 2D Elements

- Applications: Thin structures such as plates, shells, or planar problems (stress analysis in 2D).
- Types:
 - **Triangular (3-node or higher)**: Easier to mesh complex geometries; may be less accurate than quadrilaterals for the same mesh density.
 - **Quadrilateral (4-node or higher)**: Often preferred for better accuracy and efficiency in structured domains.
- Shape: Flat elements with triangular or quadrilateral geometry.

3. 3D Elements

- Applications: Solid mechanics, thermal problems, and 3D structures.
- Types:
 - **Tetrahedral (4-node or higher)**: Useful for complex geometries; easier to automate meshing.
 - **Hexahedral (8-node or higher)**: Better accuracy for structured domains but harder to mesh.
 - **Pyramidal and Wedge Elements**: Used for transitions between tetrahedral and hexahedral elements.
- Shape: Solid shapes such as tetrahedrons, hexahedrons, or wedges.

4. Shell Elements

- Applications: Thin-walled structures like aircraft fuselages, car bodies, or pipelines.
- Types:
 - Linear Shells: Simplified formulations, good for simple thin structures.
 - Nonlinear Shells: For large deformations and complex loading.

CHAPTER-10

STIFNESS MATRIX

STIFFNESS MATRIX OF A BAR ELEMENT

The primary characteristics of a finite element are embodied in the element **stiffness matrix**. For a structural finite element, the stiffness matrix contains the geometric and material behavior information that indicates the resistance of the element to deformation when subjected to loading. Such deformation may include axial, bending, shear, and torsional effects. For finite elements used in nonstructural analyses, such as fluid flow and heat transfer, the term stiffness matrix is also used, since the matrix represents **the resistance of the element to change when subjected to external influences.**

Linear spring as a finite element

A linear elastic spring is a mechanical device capable of supporting axial loading only, and the elongation or contraction of the spring is directly proportional to the applied axial load. The constant of proportionality between deformation and load is referred to as the spring constant, spring rate, or **spring stiffness k**, and has units of force per unit length. As an elastic spring supports axial loading only, we select an element coordinate system (also known as a local coordinate system) as an x axis oriented along the length of the spring, as shown.



(a) Linear spring element with nodes, nodal displacements, and nodal forces.(b) Load-deflection curve.

Assuming that both the nodal displacements are zero when the spring is undeformed, the net spring deformation is given by $\delta = u_2 - u_1$

and the resultant axial force in the spring is

 $f = k\delta = k(u_2 - u_1)$

For equilibrium,

$$f_1 + f_2 = 0$$
 or $f_1 = -f_2$,

Then, in terms of the applied nodal forces as

$$\mathbf{f}_1 = -\mathbf{k}(\mathbf{u}_2 - \mathbf{u}_1)$$

$$\mathbf{f}_2 = \mathbf{k}(\mathbf{u}_2 - \mathbf{u}_1)$$

which can be expressed in matrix form as

$$\begin{bmatrix} k & -k \\ -k & k \end{bmatrix} \begin{Bmatrix} u_1 \\ u_2 \end{Bmatrix} = \begin{Bmatrix} f_1 \\ f_2 \end{Bmatrix} \quad \text{or} \quad [k_e]\{u\} = \{f\}$$

where

 $[k_e] = \begin{bmatrix} k & -k \\ -k & k \end{bmatrix}$

Stiffness matrix for one spring element

is defined as the element stiffness matrix in the element coordinate system (or local system), $\{u\}$ is the column matrix (vector) of nodal displacements, and $\{f\}$ is the column matrix (vector) of element nodal forces.



known

The equation shows that the element stiffness matrix for the linear spring element is a 2×2 matrix. This corresponds to the fact that the element exhibits two nodal displacements (or degrees of freedom) and that the two displacements are not independent (that is, the body is continuous and elastic).

Furthermore, **the matrix is symmetric**. This is a consequence of the symmetry of the forces (equal and opposite to ensure equilibrium).

Also **the matrix is singular** and therefore not invertible. That is because the problem as defined is incomplete and does not have a solution: **boundary conditions are required**.

SYSTEM OF TWO SPRINGS [GLOBAL STIFFNESS MATRIX]



These are internal forces

Writing the equations for each spring in matrix form:

$$\begin{bmatrix} k_1 & -k_1 \\ -k_1 & k_1 \end{bmatrix} \begin{cases} u_1^{(1)} \\ u_2^{(1)} \end{cases} = \begin{cases} f_1^{(1)} \\ f_2^{(1)} \end{cases}$$
$$\begin{bmatrix} k_2 & -k_2 \\ -k_2 & k_2 \end{bmatrix} \begin{cases} u_1^{(2)} \\ u_2^{(2)} \end{cases} = \begin{cases} f_2^{(2)} \\ f_2^{(2)} \end{cases}$$

Superscript refers to element

To begin assembling the equilibrium equations describing the behavior of the system of two springs, the displacement **compatibility conditions**, which relate element displacements to system displacements, are written as:

$$u_1^{(1)} = U_1$$
 $u_2^{(1)} = U_2$ $u_1^{(2)} = U_2$ $u_2^{(2)} = U_3$

And therefore:

 $\begin{bmatrix} k_1 & -k_1 \\ -k_1 & k_1 \end{bmatrix} \begin{bmatrix} U_1 \\ U_2 \end{bmatrix} = \begin{bmatrix} f_1^{(1)} \\ f_2^{(1)} \end{bmatrix}$ $\begin{bmatrix} k_2 & -k_2 \\ -k_2 & k_2 \end{bmatrix} \begin{bmatrix} U_2 \\ U_3 \end{bmatrix} = \begin{bmatrix} f_2^{(2)} \\ f_3^{(2)} \end{bmatrix}$

Here, we use the notation $f^{(j)}_{i}$ to represent the force exerted on element *j* at node *i*. Expand each equation in matrix form:

$$\begin{bmatrix} k_1 & -k_1 & 0 \\ -k_1 & k_1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} U_1 \\ U_2 \\ 0 \end{bmatrix} = \begin{bmatrix} f_1^{(1)} \\ f_2^{(1)} \\ 0 \end{bmatrix}$$
$$\begin{bmatrix} 0 & 0 & 0 \\ 0 & k_2 & -k_2 \\ 0 & -k_2 & k_2 \end{bmatrix} \begin{bmatrix} 0 \\ U_2 \\ U_3 \end{bmatrix} = \begin{bmatrix} 0 \\ f_2^{(2)} \\ f_3^{(2)} \end{bmatrix}$$

Summing member by member:

$$\begin{bmatrix} k_1 & -k_1 & 0 \\ -k_1 & k_1 + k_2 & -k_2 \\ 0 & -k_2 & k_2 \end{bmatrix} \begin{bmatrix} U_1 \\ U_2 \\ U_3 \end{bmatrix} = \begin{bmatrix} f_{1}^{(1)} \\ f_{2}^{(1)} + f_{2}^{(2)} \\ f_{3}^{(2)} \end{bmatrix}$$

Next, we refer to the free-body diagrams of each of the three nodes:

$$f_{1}^{(1)} = F_1$$
 $f_{2}^{(1)} + f_{2}^{(2)} = F_2$ $f_{3}^{(2)} = F_3$

Final form:

$$\begin{bmatrix} k_1 & -k_1 & 0\\ -k_1 & k_1 + k_2 & -k_2\\ 0 & -k_2 & k_2 \end{bmatrix} \begin{bmatrix} U_1\\ U_2\\ U_3 \end{bmatrix} = \begin{bmatrix} F_1\\ F_2\\ F_3 \end{bmatrix}$$
(1)

Where the stiffness matrix:

$$[K] = \begin{bmatrix} k_1 & -k_1 & 0\\ -k_1 & k_1 + k_2 & -k_2\\ 0 & -k_2 & k_2 \end{bmatrix}$$

PROPERTIES OF STIFFNESS MATRIX

Note that the system stiffness matrix is:

(1) symmetric, as is the case with all linear systems referred to orthogonal coordinate systems;

(2) singular, since no constraints are applied to prevent rigid body motion of the system;

(3) the system matrix is simply a superposition of the individual element stiffness matrices with proper assignment of element nodal displacements and associated stiffness coefficients to system nodal displacements.

CH-11412 :- Problems on 1D flements of FEM



$$[K_{1}] = \frac{1963.49 \times 2 \cdot 1 \times 10^{5}}{300} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$

$$= 13 \cdot 74 \times 10^{5} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$

(iii) Global Stiffness Matrix

$$[K] = [K_{1}] = 13 \cdot 74 \times 10^{5} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$

Global nodal displacement vector

$$\{Q_{1}\} = \begin{cases} P_{1} \\ P_{2} \end{bmatrix}$$

Global load vector

$$\{F_{1}\} = \begin{cases} F_{1} \\ P_{2} \end{bmatrix} = \begin{cases} 0 \\ 1500 \end{bmatrix}$$

(iv) Equilibrium condition:

$$\{F_{1}\} = [K_{1}] \{Q_{1}\}$$

$$\begin{cases} 0 \\ 1500 \end{bmatrix} = 13 \cdot 74 \times 10^{5} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \{Q_{1}\}$$

$$\begin{cases} 0 \\ 1500 \end{bmatrix} = 13 \cdot 74 \times 10^{5} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \{Q_{2}\}$$

$$\begin{cases} 0 \\ 1500 \end{bmatrix} = 13 \cdot 74 \times 10^{5} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \{Q_{2}\}$$

(w) Attalying boundary condition:

$$P_{1} = 0 (Fixed - end)$$

$$\therefore \begin{cases} 0 \\ 1500 \end{bmatrix} = 12 \cdot 74 \times 10^{5} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \{Q_{2}\}$$

$$o_{1} = 0 = 12 \cdot 74 \times 10^{5} \times Q_{2}$$

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$$o_{1} = 0 = 12 \cdot 74 \times 10^{5} \times Q_{2}$$

$$o_{2} = 0 \cdot 00 = 10 = 10 \text{ mm}$$

$$vector id$$

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92 4 Steel sod Subjectuel to tension is modelled by
interplacement as shown in figure. Determine the nodal
displacement and the axial stress in each element and reaction
borres. E = 2.1×10⁵ N[mm², Poisson's ratio = 0.3

13 A steel rod subjected to compression is modelled by two bar elements as shown in figure. Determine the nodal displacements and anial stress in each element. Take E = 207 GPa; A = 500 mm².



<u>Sol</u>" - (i) Finite Element (FE) Model: $F_{1} \xrightarrow{q_{1}} F_{2} \xrightarrow{q_{2}} \xrightarrow{q_{3}} F_{3} \xrightarrow{q_{1}} \xrightarrow{q_{2}} \xrightarrow{q_{3}} \xrightarrow$ $E = E_1 = E_2 = 2079 Ra = 207 \times 10^3 N/mm^2$

A = A1 = A2 = 500 mm2 L= 1, = 12 = 0.5m=500mm F3 = -12 KN (opposite to 2-direction)

$$\begin{aligned} & \text{For element 1,} \\ & [K_i] = \frac{A_1 E_1}{L_1} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \\ & = \frac{500 \times 207 \times 10^3}{500} \begin{bmatrix} -1 & -1 \\ -1 & 1 \end{bmatrix} = 10^3 \begin{bmatrix} 207 & -207 \\ -207 & 207 \end{bmatrix} \\ \end{aligned}$$

For element 2;

$$\begin{bmatrix} k_2 \end{bmatrix} = \frac{A_2 E_2}{L_2} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$

$$\begin{bmatrix} k_2 \end{bmatrix} = \frac{500 \times 207 \times 10^3}{500} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$

$$\begin{bmatrix} k_2 \end{bmatrix} = 10^3 \begin{bmatrix} 207 & -207 \\ -207 & 207 \end{bmatrix}$$

$$\begin{bmatrix} k \end{bmatrix} = \begin{bmatrix} k_1 \end{bmatrix} + \begin{bmatrix} k_2 \end{bmatrix}$$

$$\begin{bmatrix} k \end{bmatrix} = \begin{bmatrix} k_1 \end{bmatrix} + \begin{bmatrix} k_2 \end{bmatrix}$$

$$\begin{bmatrix} k \end{bmatrix} = 10^3 \begin{bmatrix} 207 & -207 & 0 \\ -707 & 414 & -207 \\ 0 & -207 & 207 \end{bmatrix}$$

$$\begin{bmatrix} 104al \text{ nodal dieplacement vector;} \\ \end{bmatrix} = \begin{cases} 91 \\ 92 \\ 192 \\ 193 \\ 192 \\ 193 \\ 192 \\ 193 \\ 192 \\ 193 \\ 192 \\ 193 \\ 192 \\ 193 \\ 192 \\ 193 \\ 192 \\ 193 \\ 192 \\$$

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414 ×10³ 92 - 207 ×10³ 9₃ = 0
-207×10³ 9₂ + 207×10³ 9₃ = -12000

$$\therefore 9_2 = -0.05797 \text{ mm}$$

 $9_2 = -0.11594 \text{ mm}$
 $9_3 = -0.11594 \text{ mm}$
 $100 \text{ Atress in each element '},
 $5 = \frac{\text{EeE}-1}{10} \int 9_{11}^{2} \int 9_{11}^{2}$$

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(VII) Reaction at support:

$$R\{\frac{1}{2} = [K] \{ 8 \frac{1}{2} - \frac{1}{2} F \}$$

 $= \frac{10}{10} \begin{bmatrix} 207 - 207 & 0 \\ -907 & 414 - 207 \\ 0 & -207 & 207 \end{bmatrix} \begin{bmatrix} -0.05997 \\ -0.05997 \\ -0.011534 \end{bmatrix} - \begin{bmatrix} 0 \\ -12000 \\ -12000 \\ -0.011534 \end{bmatrix}$
Abbles Simplification,
 $\begin{cases} R_1 \\ R_2 \\ R_3 \\ \end{bmatrix} = \begin{cases} 12000 \\ 0 \\ 0 \\ \end{bmatrix} N \xrightarrow{Ans}$
 $R_2 \\ R_3 \\ \end{bmatrix} = \begin{cases} 0 \\ 0 \\ 0 \\ 0 \\ \end{bmatrix} N \xrightarrow{Ans}$
 $g[4] A load of $\beta = 60 \text{ KN is applied as shown in big-}$
Determine the following s-
 $@ Nodel displacement @ stress in each member,$
 $Given: - E = 20 \times 10^3 \text{ N/mm}^2, \rhooisson's vatio, \mu = 0.3$
 $A = 250 \text{ mm}^2$.$

Solution'-
() Finite element Model:-

$$q_1$$
, q_2 , q_3
 $F = \frac{e_1}{1 \times 1}$, $\frac{e_2}{2 \times 12^3}$, $\frac{1}{1 \cdot 2 \times 12^{-3}}$, $\frac{1}{1 \cdot 2 \times 12^{-$

FOR element 2 $[K_2] = \frac{250 \times 20 \times 10^3}{150} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$ = 0.33 ×10 [1-1] (ii) Global Stiffness matrix $[K] = [K_1] + [K_2]$ $= 0.33 \times 10^{5} \left(\begin{array}{c} 1 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 1 \end{array} \right)$ gtokal Nodal displacement vector $\{g\} = \{q_1 \\ q_2\}$ global toad vector $\{F\} = \{F_1 - K_{13} a_3\} \\ \{F_2 - K_{23} a_3\} \\ \{F_2 - K_{33} a_3\} \\ \{F_3 - K_{33} a_3\} \\ \{$ Where a3 = Max. displacement = 1.2 mm (4 Equilibrium condition [K] 398 = 3F7 Jubstituting the values of [k], $\{9\}, \{F\}, We get,$ $\begin{bmatrix} 0.33 & -0.33 & 0 \ 1 \\ -0.33 & 0.66 & -0.33 \ 92 \ = \ -0.33 \end{bmatrix}$

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Q5: Consider the stepped bar as shown in figurekelow. Determine the nodal displacement, stress in each element and reaction forces.



Solⁿ: DFinite Element model: - $F_1 = P_1$ $F_2 = P_2$ $F_2 = P_2$ $F_2 = P_2$ $F_3 \rightarrow F_3$ $F_4 = 1_2$ $F_4 = 1_2$ $F_2 = 0.7 \times 10^5 N | mm^2$, $A_1 = 900 mm^2$, $I_1 = 600 mm$ $F_2 = 600 mm^2$, $I_2 = 500 mm$

(2) Elemental stiftmess matrix:-
The stiftmess matrix for the bar element is given by

$$[ke] = \frac{AeEe}{le} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$

for element L. $[k_1] = 900 \times 2.0 \times 10^{5} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = 10^{5} \begin{bmatrix} -3 & -3 \\ -3 & 2 \end{bmatrix}$

For element 2,
$$[k_2] = \frac{600 \times 0.7 \times 10^5}{500} \begin{bmatrix} 1 - 1 \\ -1 \end{bmatrix} = 10^5 \begin{bmatrix} 0.84 & -0.84 \\ -0.84 & 0.84 \end{bmatrix}$$



Q.6 Find nodal displacement, storess in each element and reaction torces for the following problem. Given $E_1 = 70 \times 10^3 \text{ N/mm}^2$, $E_2 = 200 \times 10^3 \text{ N/mm}^2$, $A_1 = 2400 \text{ mm}^2$, $A_2 = 600 \text{ mm}^2$, Y = 0.3



Solution: -
(D) FE Model:-
Modelling the given stepped bar using two bar
element as shown in tigure:-

$$F_1$$
 (c) F_2 (c) F_3
 F_1 (c) F_2 (c) F_3 (c) F_3 (c) F_4
 $I = 200 \text{ mm}^2$, $E_2 = 200 \text{ x1} 0^3 \text{ N/mm}^2$
 $A_1 = 2400 \text{ mm}^2$, $A_2 = 600 \text{ mm}^2$.

(2) Elemental stiftness matrix: The stiftness matrix for the stepped bar is given by. $\begin{bmatrix} K_e \end{bmatrix} = \frac{A_e E_e}{L_e} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$ $\frac{\text{for element 1}}{\begin{bmatrix} K_1 \end{bmatrix} = \frac{A_1 E_1}{L_1} \begin{bmatrix} 1-1 \\ -1 & 1 \end{bmatrix}} = \frac{2400 \times 70 \times 10^3}{300} \begin{bmatrix} 1-1 \\ -1 & 1 \end{bmatrix} = 10^5 \begin{bmatrix} 5 \cdot 6 & -5 \cdot 6 \\ -5 \cdot 6 & 5 \cdot 6 \end{bmatrix}$ $\begin{bmatrix} K_1 \end{bmatrix} = \frac{A_1 E_1}{L_1} \begin{bmatrix} 1-1 \\ -1 & 1 \end{bmatrix} = \frac{2400 \times 70 \times 10^3}{300} \begin{bmatrix} 1-1 \\ -1 & 1 \end{bmatrix} = 10^5 \begin{bmatrix} 5 \cdot 6 & -5 \cdot 6 \\ -5 \cdot 6 & 5 \cdot 6 \end{bmatrix}$ $\begin{bmatrix} For element 2r, & 3r = 1 \\ 1 & 1 \end{bmatrix} = 10^5 \begin{bmatrix} 5 \cdot 6 & -5 \cdot 6 \\ -5 \cdot 6 & 5 \cdot 6 \end{bmatrix}$

$$\frac{[K_2]}{[K_2]} = \frac{A_2 E_2 \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}}{[L_2]} = \frac{600 \times 200 \times 10}{[400]} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = 10 \begin{bmatrix} 5 & 3 \\ -3 & 3 \end{bmatrix}$$

(3) Global stiftness matrix:
The global stiftness matrix for stepped bar is given by
[K] = [K_1] + [K_2] = 10^5 \begin{bmatrix} 5 \cdot 6 & -5 \cdot 6 & 0 \\ -5 \cdot 6 & 8 \cdot 6 & -3 \\ 0 & -3 & 3 \end{bmatrix}

12

global nodal displacement vector: - ggy = 292 Global load vector: $\{F_i\} = \begin{cases} 0\\ F_2 \\ F_2 \end{cases} = \begin{cases} 0\\ 200 \times 10^3 \\ 0 \end{cases}$ @ equilibrium condition:. [K]{8} = {F} substituting the values of [K], [] and {F} we get, $10^{5} \begin{bmatrix} 5.6 & -5.6 & 0 \\ -5.6 & 8.6 & -3 \\ 0 & -3 & 3 \end{bmatrix} \begin{bmatrix} 9_{1} \\ 9_{2} \\ 9_{3} \end{bmatrix} = \begin{bmatrix} 0 \\ 200 \times 10^{3} \\ 0 \end{bmatrix}$ (3) Applying boundary conditions From tigure; 9,=0 joue to bixed end Note: - Using elimination method of handling boundary conditions, eliminating corresponding Yow and column with respect to the known boundary condition, i.e. 9, =0 & 92 =0, we get. $8.6 \times 10^5 9_2 = 200 \times 10^3$ 9/2 = 0.232558 mm The nodal displacement vector is { } } = { 0.232558 } mm # (Stress in each element The stress in a 10 bar element is given by- $\sigma_{e} = \frac{E_{e}}{1e} \left[-1 \right] \left\{ \begin{array}{c} 9i \\ 9i \\ 1 \end{array} \right\}$ Where i=e i=node number e= no. of element

13

$$\frac{For element 2}{5_2 = \frac{E_2}{L_2} [-1] \left\{ \frac{q_2}{q_3} \right\} = \frac{200 \times 10^5}{400} [-1] \left\{ \begin{array}{c} 0.23255 \right\} = -116.275 \text{ N/mm}^2}{400} \text{ Ans} \right\}$$

Atter Simplification, we get

$$\begin{cases} R_{1} \\ R_{2} \\ R_{3} \\ \end{cases} = \begin{cases} -130228 \\ 0 \\ -69765 \\ \end{cases} N Ams$$

Q.7. Consider the bar loaded as shown in figure. Determine the nodal displacement, stress in each element and reaction forces. Qiven: P = 300 kN, $E = 200 \times 10^3 \text{ N/mm}^2$, $\gamma = 0.3$, $A_1 = 250 \text{ m}^2$ $A_2 = 400 \text{ mm}^2$

$$\frac{fel^{h}}{150 \text{ mm}} = \frac{300 \text{ mm}}{300 \text{ mm}} = \frac{1}{3} \xrightarrow{1}{150 \text{ mm}} \xrightarrow{1}{150 \text{ m}} \xrightarrow{1}$$

$$[k_e] = \frac{A_e E_e}{L_e} \begin{bmatrix} 1 & -1 \\ -L & 1 \end{bmatrix}$$

÷,

The displacement vector is [6

$$\{P_{i}\} = \begin{cases} 0 & 62246 \\ 0 & 34602 \end{cases}$$
 mm Ans
(6) The stress in each element:
 $for element L,$
 $S_{1} = \frac{E_{1}}{C_{1}} [-1,1] \begin{cases} P_{1} \\ P_{2} \\ P_{2} \\ P_{3} \\ P_{4} \\ P_{5} \\ P_{$



Que te the stiffness matrix for the CST 2D element shown below: Coordinates in mm. Assume plain stress conditions. E = 200 gla, Y = 0.03 (Poisson's vatio), Thickness $= 1 \text{ cm} \cdot \frac{1}{10,23}$ $= 1 \text{ cm} \cdot \frac{2}{155,0}$ Nodal displacement are. $= 200 \text{ gla} \cdot \frac{2}{155,0}$ Nodal displacement are.

1 + (0, - 40)

 $u_3 = 2 mm, V_1 = 1 mm_2$

Also find the stress in

V2=0, V3=100m

the element. Solution . - $(2e_1, y_1) = (0, -40); (2e_2, y_2) = (55, 0); (x_3, y_3) = (0, 25)$ $(x_1, y_1) = (0, -4); (x_2, y_2) = (5.5, 0); (x_3, y_3) = (0, 2.5)$ (for simplification converted the coordinates of CST 2D elements from mm to cm) B1= 42-43 = 0-2.5 = -2.5 $\beta_2 = [\gamma_3 - j_1] = 2 \cdot 5 - (-4) = 6 \cdot 5$ B3=(y-y2)=-4-10=-4 $\gamma_{l} = -(\chi_{2} - \chi_{3}) = -(5 \cdot 5 - 6) = -5 \cdot 5$ $Y_2 = -(x_3 - x_1) = -(0 - 0) = 0$ $\gamma = -(24 - 22) = -(0 - 5 \cdot 5) = 5 \cdot 5$ Let A be the area of triangle. $\mathbf{B}\mathbf{A} = \frac{1}{2} \begin{bmatrix} 1 & \mathbf{x}_1 & \mathbf{y}_1 \\ 1 & \mathbf{x}_2 & \mathbf{y}_2 \\ 1 & \mathbf{x}_3 & \mathbf{y}_3 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 & \mathbf{0} & -\mathbf{y}_1 \\ 1 & 5 \cdot 5 & \mathbf{0} \\ 1 & 5 \cdot 5 & \mathbf{0} \end{bmatrix} = \mathbf{0} \quad 17 \cdot \mathbf{8} \quad 75 \quad cm^2$

		[A.122	0.07	-0.007	-0.0000	- hoat	-0.0028
[K]	= 200 6	0-152	0.07	-0.0004	-0.0046	0.0015	-0.021
	- 3929710	0.004	-D ANT	0.033	0	-0-0007	0.0084
		-0.0127	-0.0089	0.033	0,0116	-0.0203	5.0071
		-0.0098	-0.0042	0.0202	0.0078	0.0018	-0.0071
		0.0035	0-0014	2010203	0.0018	0.0208	0.0112
		-0.0028	-0.021	0.0084	-0.0071	-0.0112	-0.0282

Reaction force calculation:

 $\begin{bmatrix} K \end{bmatrix} \begin{bmatrix} U_{1}^{2} = \{F\} \\ 10^{6} \begin{bmatrix} 5+19 & 2.75 & -5 & -3.89 & -0.181 & 1\cdot1 \\ 2.75 & 10 & -3.3 & -1.77 & 0.555 & -8.25 \\ -5 & -3.3 & 13 & 0 & -8 & 3.3 \\ -3.85 & -1.77 & 0 & 4.55 & 3.855 & -2.77 \\ -0.181 & 0.55 & -8 & 3.855 & 8.17 & -4.9 \\ 1.1 & -8.25 & 3.3 & -2.79 & -4.9 & 11 \end{bmatrix} \begin{bmatrix} U_{1} \\ V_{1} \\ V_{1} \\ V_{1} \\ V_{1} \\ U_{2} \\ V_{2} \\ V_{3} \\ V_{3} \end{bmatrix} = \begin{bmatrix} F_{1} \\ F_{1} \\ F_{3} \\$

Affly boundary conditions:

$$u_1 = 0.1 \text{ cm}, W_2 = 0.1 \text{ cm}, u_2 = 0.05 \text{ cm}, v_2 = 0, u_3 = 0.2 \text{ cm}$$

 $v_2 = 0.1 \text{ cm}$
After simplification, we get
 $F_{1n} = 617.8 \text{ kN}, F_{1y} = 395 \text{ kN}, F_{22} = -1450 \text{ kN}, F_{2y} = -71 \text{ kN}$
 $F_{32} = 830.9 \text{ kN}, F_{3y} = -330 \text{ kN}$
Elemental stress matrix
 $v_{5-1} = [D]\{E\}$.
 $= CO][G]\{V\}$
 $\begin{cases} v_1 \\ -v_2 \\ -v_3 \\ -v_4 \\ -v_4 \\ -v_1 \\ -v_1 \\ -v_2 \\ -v_1 \\ -v_1 \\ -v_1 \\ -v_2 \\ -v_1 \\ -v_1 \\ -v_2 \\ -v_1 \\ -v_2 \\ -v_2 \\ -v_1 \\ -v_2 \\ -v_1 \\ -v_2 \\ -v_1 \\ -v_1 \\ -v_2 \\ -v_1 \\ -v_1 \\ -v_2 \\ -v_2 \\ -v_1 \\ -v_2 \\ -v_2 \\ -v_1 \\ -v_2 \\ -v_2 \\ -v_1 \\ -v_2 \\ -v_1 \\ -v_2 \\ -v_1 \\ -v_2 \\ -v_1 \\ -v_2 \\ -v_2 \\ -v_1 \\ -v_2 \\ -v_2 \\ -v_2 \\ -v_1 \\ -v_2 \\ -v_2 \\ -v_2 \\ -v_2 \\ -v_1 \\ -v_2 \\ -v_$